Single Maths B: Introduction to Probability

Overview

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1 Introduction to Probability

1.1 Introduction

What is probability?

- Probability the mathematical study of uncertainty
- Probability is a useful concept like *mass* or *energy* and its behaviour is extremely simple. It is attached to events and satisfies some very simple rules.
- Some events can be said to be uncertain we do not know their outcomes before they occur and we observe what happened.
- Standard mathematics deals only with the certain, so we need some new tools which will allow us to capture, manipulate and reason with this uncertainty
- We begin by quantifying this uncertainty by assigning numbers to each of the possible outcomes to give a measure of "what is likely to happen."
- Larger values will indicate a particular outcome is more likely. Lower numbers will indicate an outcome is less likely.

$$P [fair coin lands heads] = \frac{1}{2},$$
$$P [climate change] = ?$$

Why is it useful?

- Probability can be fundamental to our understanding of the world Quantum mechanics, statistical mechanics, Ising model of magnetism, genetics
- Probability can used to build models of complex systems or phenomena Epidemics, population growth, chemical interactions, financial markets, routing within networks
- Probability theory leads to the discipline of *statistics*
- Statistics can be used to analyse data gathered from experiments, and drawing conclusion under uncertainty

Important to all the experimental sciences

1.2 Events

- Probability theory is used to describe any process whose outcome is not known in advance with certainty. In general, we call these situations *experiments* or *trials*.
- The set of all possible outcomes of an experiment (or random phenomenon) is the sample space S.
- An *event* is a subset of the outcomes in a sample space.

• We treat events as *sets*, and so have three basic operations to combine and manipulate them.

Event operations

- Let A, B be some events.
- The event not A is A^c (the complement), which is the set of all outcomes in S and not in A.
- The event A or B is $A \cup B$ (the union), which the set of all outcomes in A, or in B or in both.
- The event A and B is $A \cap B$ (the *intersection*), which is the set of all outcomes that are both in A and in B.

Disjoint Events

- Two (or more) events are called *disjoint* (or *incompatible*, or *mutually exclusive*) if they cannot occur at the same time.
- The event which contains no outcomes is written \emptyset , and is called the *empty set*.
- So if A and B are disjoint, then we must have $A \cap B = \emptyset$

Example: Cluedo

Dr. Black has been murdered! There are four possible suspects: Colonel Mustard, Professor Plum, Miss Scarlet, Reverend Green. There are three possible murder weapons: Candlestick, Lead Piping, Rope. There can be only one murderer and one murder weapon.

Working with Events

The following basic set rules will be useful when working with events:

Event Rules

Commutivity:	
$A \cup B = B \cup A,$	$A\cap B=B\cap A$
Associativity:	
$(A \cup B) \cup C = A \cup (B \cup C),$	$(A \cap B) \cap C = A \cap (B \cap C)$
Distributivity:	
$(A \cap B) \cup C = (A \cup C) \cap (B \cup C),$	$(A\cup B)\cap C=(A\cap C)\cup(B\cap C)$
DeMorgan's laws:	
$(A \cup B)^c = A^c \cap B^c,$	$(A \cap B)^c = A^c \cup B^c$

1.3 Probability

Axioms of Probability

- We associate a probability with every outcome (and hence every event) in the sample space \mathcal{S} .
- For any event A (i.e. any subset of S) we define a number P[A] which we call the *probability* of A.
- P[A] is the quantification of our uncertainty about the occurrence of the event A.
- Note: A is an event which is a set, P[A] is a probability which is a number, and $P[\cdot]$ is a function which maps events to numbers.

The Axioms of Probability (Komolgorov)

- 1. $0 \le P[A] \le 1$ probability is a number in the interval [0, 1].
- 2. P[S] = 1 some outcome from the sample space *must* happen; certain events have probability 1.
- 3. If A and B are disjoint events, then $P[A \cup B] = P[A] + P[B]$

• We can think of these three axioms as the "Laws of Probability"

Consequences of the Axioms

• These axioms imply some additional useful properties of probabilities:

Consequences to the Axioms of Probability

- 1. $P[A^c] = 1 P[A]$.
- 2. $P[\emptyset] = 0$ impossible events have probability zero
- 3. In general for any events A and B, $P[A \cup B] = P[A] + P[B] P[A \cap B]$.
- 4. If A and B are events, and A contains all of the outcomes in B and more, then we say that B is a subset of A, $B \subset A$ and P[B] < P[A].

Probability Interpretations

- There are three different interpretations of probability:
 - 1. Classical probability: considers only sample spaces where every outcome is equally likely. If we have n outcomes in our sample space (#S = n), then for every outcome $s \in S$ and event $A \subseteq S$ we have

$$P[{s}] = \frac{1}{n},$$
 $P[A] = \frac{\#A}{n} = \frac{\text{number of ways A can occur}}{\text{total no. outcomes}}.$

2. Frequentist probability: Suppose we repeat the trial n times, and count the number of trials where the event A occurred. The frequentist approach claims that the probability of the event A occurring is the *limit of its relative frequency* in a large number of trials:

$$\mathbf{P}\left[A\right] = \lim_{n \to \infty} \frac{n_A}{n}$$

- 3. **Subjective probability** views the probability of an event as a measure of an individual's degree of belief that that event will occur.
- Regardless of which interpretation of probability we use, all probabilities must follow the same laws and axioms to be coherent.

Examples

- The probability that student A will fail a certain examination is 0.5, for student B the probability is 0.2, and the probability that both A and B will fail the examination is 0.1. What is the probability that at least one of A and B will fail the examination?
- In the Cluedo example, suppose the probabilities of the guilty suspect are as follows:

Guilty Suspect	Μ	Р	\mathbf{S}	G
Probability	0.5	0.25	0.1	p

- 1. Deduce the value of the missing probability p.
- 2. Find the probability that both Col. Mustard and Rev. Green are innocent.

Suggested Exercises: Q1–11.

1.4 Conditional Probability

Conditional Probability and Independence

- For any two events A, B, the notation P[A|B] means the *conditional* probability that event A occurs, given that the event B has already occurred.
- Conditional probabilities are obtained either directly or by using the *conditional probability rule*:

The conditional probability rule

$$P[A|B] = \frac{P[A \cap B]}{P[B]}, \text{ for } P[B] > 0.$$

• Rearranging this equation gives the *multiplication rule*, useful in simplifying probabilities: for any two events A, B,

The multiplication rule

$$\mathbf{P}[A \cap B] = \mathbf{P}[A|B]\mathbf{P}[B].$$

Independence

- Two events are said to be *independent* when the occurrence of one has no bearing on the occurrence of the other.
- In terms of probability, if A, B are independent then

$$\mathbf{P}\left[A|B\right] = \mathbf{P}\left[A\right]$$

as the knowledge that B occurred is irrelevant.

• For independent events A,B, the multiplication rule can then be simplified,

$$P[A \cap B] = P[A] P[B].$$

• Note: Beware of confusing independent events with disjoint events. Independent events do not affect each other in any way, whereas disjoint events cannot occur together – disjoint events are very much dependent on each other.

Example: Two Dice

Two fair dice are rolled, what is the probability that the sum of the two numbers that appear is even?

Example: Nuclear Power Station

Suppose that a nuclear power station has three separate (and independent) devices for detecting a problem and shutting down the reactor. Suppose that each device has a probability of 0.9 of working correctly. In the event of a problem, what is the probability that the reactor will be shut down?

Partitions

- Suppose that n events E_1, \ldots, E_n are *disjoint*, and suppose that exactly one must happen. Such a collection of events is called a *partition*.
- Now we can write any other event A in combination with this partition: in general,

$$P[A] = P[A \cap E_1] + P[A \cap E_2] + ... + P[A \cap E_n],$$

• Using the multiplication rule, we can simplify this to get

The partition theorem (or theorem of total probability)

 $P[A] = P[A|E_1] P[E_1] + P[A|E_2] P[E_2] + ... + P[A|E_n] P[E_n].$

• Often, this is the most convenient way of getting at certain hard-to-think-about events: to associate them with a suitable partition, and then use conditional probability to simplify matters.

Bayes Theorem

• For any two events A, B, the multiplication rule gives the formula

$$\mathbf{P}\left[A \cap B\right] = \mathbf{P}\left[A|B\right]\mathbf{P}\left[B\right].$$

• Another equivalent formula is obviously

$$P[A \cap B] = P[B \cap A] = P[B|A]P[A].$$

• By equating these two formulae and rearranging, we obtain the formula known as

Bayes theorem

$$P[A|B] = \frac{P[B|A]P[A]}{P[B]}.$$

• It is useful mainly as a way of "inverting" probabilities. Often, the probability in the denominator must be calculated using the simplifying method shown in the last section; i.e. via a *partition*.

Example: Diagnosing Diseases

A clinic offers a test for a very rare and unpleasant disease which affects 1/10000 people. The test itself is 90% reliable, i.e. test results are positive 90% of the time given you have the disease. If you don't have the disease the test reports a false positive only 1% of the time. You decide to take the test. What is the probability that the test is positive? Your test returns a positive result. What is the probability you have the disease now?

Suggested Exercises: Q2–17.

2 Random Variables

- A *random variable* (rv) is a variable which takes different numerical values, according to the different possible outcomes of an experiment or random phenomenon.
- Random variables are *discrete* if they only take a finite number of values (e.g. outcome of a coin flip).
- The opposite is a *continuous* random variable with an infinite sample space (e.g. a real-valued measurement).

2.1 Discrete Random Variables

Discrete Random Variables and Probability Distributions

• A discrete random variable X is defined by a pair of two lists

Possible				
values:	x_1	x_2	x_3	
Attached				
probabilities:	$\Pr\left[X=x_1\right]$	$P\left[X=x_2\right]$	$\mathbf{P}\left[X=x_3\right]$	

- This collection of all possible values with their probabilities is called the *probability distribution* of X.
- The probabilities in a probability distribution must:
 - 1. be non-negative $P[X = x_i] \ge 0, \forall i$
 - 2. add to one $-\sum_{i} P[X = x_i] = 1$

Joint and Marginal Distributions

• When we have two (or more) random variables X and Y, the *joint probability distribution* is the table of every possible (x, y) value for X and Y, with the associated probabilities P[X = x, Y = y]:

• Given the joint distribution for the random variables (X, Y), we can obtain the distribution of X (or Y) alone – the marginal probability distribution for X (or Y) – by summing across the rows or columns:

$$P[X = x] = \sum_{\text{all } y} P[X = x, Y = y]$$

Example: Discrete Random Variables

Let X be the random variable which takes value 3 when a fair coin lands heads up, and takes value 0 otherwise. Let Y be the value shown after rolling a fair dice. Write down the distributions of X, and Y, and the joint distribution of (X, Y). You may assume that X and Y are independent. Thus find the probability that X > Y

Suggested Exercises: Q18–22.

2.2 Continuous Random Variables

Continuous random variables

- Discrete rvs only make sense when our sample space is finite.
- When our experimental outcome is a measurement of some quantity, then our sample space is actually part of the real line and so is infinite.
- A random variable X which can assume every real value in an interval (bounded or unbounded) is called a *continuous random variable*.
- Since our sample space is now infinite we cannot write down a table of probabilities for every possibly outcome to describe the distribution of X.
- Instead, the probability distribution for X is described by a probability density function (pdf), f(x), which is a function that describes a curve over the range of possible values taken by the random variable.

Continuous random variables

- A valid probability density function, f(x), must
 - 1. be non-negative everywhere: $f(x) \ge 0, \forall x$,
 - 2. integrate to 1: $\int_{-\infty}^{\infty} f(x) dx = 1$,
- The probability for a range of values is given by the area under the curve.

$$P[a \le X \le b] = \int_{a}^{b} f(x) \, dx$$

Note: $f(x) \neq P[X = x]$ — probability densities *are not* probabilities

• We can describe the probability by the function

$$F(x) \equiv \int_{-\infty}^{x} f(y) \, dy = \mathbf{P} \left[X \le x \right]$$

which is called the *cumulative distribution function* (cdf) of X.

• We also have the result that f(x) = F'(x).

Joint and Marginal Distributions

- When we have two (or more) continuous random variables, we describe them via their joint probability density function $f_{xy}(x, y)$, which satisfies the usual conditions for pdfs
- The probability that X and Y fall into some region A of the xy-plane is then

$$P[(X,Y) \in A] = \int_A \int f_{xy}(x,y) \, dx \, dy$$

• Given the joint pdf $f_{xy}(x, y)$, we can obtain the marginal pdf of x or y by integrating out the other variable

$$f_x(x) = \int_{-\infty}^{\infty} f_{xy}(x, y) \, dy$$

• When two continuous random variables x and y are *independent*, their joint pdf can be expressed as the *product* of the marginal pdfs

$$f_{xy}(x,y) = f_x(x) f_y(y)$$

Example: The Exponential Distribution

Let X be a continuous random variable with probability density function:

$$f(x) = \begin{cases} \beta e^{-\beta x} & \text{for } x > 0, \\ 0 & \text{for } x \le 0. \end{cases}$$

Show that f(x) is a valid probability density function when $\beta > 0$. Find the cdf of X, and hence P[X > 3].

Suggested Exercises: Q23–26.

3 Expectation and Variance

Distribution Summaries

- The distribution of a random variable X contains all of the probabilistic information about X.
- However, the entire distribution of X can often be too complex to work with.
- Summaries of the distribution, such as its average or spread can be useful for conveying information about X without trying to describe it in its entirety.
- Formally, we measure the average of the distribution by calculating its expectation, and we measure the spread by its variance.

3.1 Expectation

• Suppose that X has a discrete distribution, then the expectation of X is given by

$$\mathbf{E}\left[X\right] = \sum_{\text{all } x} x \mathbf{P}\left[X = x\right]$$

• If a random variable X has a continuous distribution with a pdf $f(\cdot)$, then the expectation of X is defined as:

$$\operatorname{E}[X] = \int_{-\infty}^{\infty} x f(x) \, dx$$

• The value E(X) is the theoretical average of the probability distribution. Because of this, it is often referred to it as the *mean* or *average* for the distribution.

Properties of Expectation

• Expectation of a function: If X is a random variable, then the expectation of the function r(X) is given by

$$\mathbf{E}\left[r(X)\right] = \sum_{\text{all } x} r(x) \mathbf{P}\left[X = x\right], \qquad \text{ or } \mathbf{E}\left[r(X)\right] = \int_{-\infty}^{\infty} r(x) f(x) \ dx$$

• Linearity: If Y = a + b X where a and b are constants, then

$$\operatorname{E}\left[Y\right] = a + b\operatorname{E}\left[X\right].$$

• Additivity: If X_1, X_2, \ldots, X_n are any random variables then

$$E[X_1 + X_2 + \dots + X_n] = E[X_1] + E[X_2] + \dots + E[X_n]$$

• If X_1, X_2 are any pair of *independent* random variables then

$$\mathbf{E}\left[X_1 X_2\right] = \mathbf{E}\left[X_1\right] \mathbf{E}\left[X_2\right]$$

3.2 Variance

• Suppose that X is a random variable with mean $\mu = E[X]$. The variance of X, denoted Var[X], is defined as follows:

$$\operatorname{Var}\left[X\right] = \operatorname{E}\left[(X - \mu)^2\right].$$

- Note: Since Var [X] is the expected value of a non-negative random variable $(X \mu)^2$, it follows that Var $[X] \ge 0$.
- We can re-write the variance formula in the following simpler form:

$$\operatorname{Var}\left[X\right] = \operatorname{E}\left[X^{2}\right] - \operatorname{E}\left[X\right]^{2}.$$

• The standard deviation of a random variable is defined as the square root of the variance: $SD[X] = \sqrt{Var[X]}$.

Properties of Variance

• For constants *a* and *b*:

$$\operatorname{Var}\left[a+bX\right] = b^{2}\operatorname{Var}\left[X\right], \qquad \qquad \operatorname{SD}\left[a+bX\right] = b \,\operatorname{SD}\left[X\right]$$

• If X_1, \ldots, X_n are *independent* random variables, then

$$\operatorname{Var} [X_1 + \dots + X_n] = \operatorname{Var} [X_1] + \dots + \operatorname{Var} [X_n].$$

Example: National Lottery

The National lottery has a game called 'Thunderball'. You pick 5 numbers in the range 1-34 and one number (the Thunderball number) in the range 1-14. You win a prize if you match at least two numbers, including the Thunderball number. Let X be the amount you win in a single game. The probability distribution for X is given below. Find the expectation and variance of X.

k, Prize \pounds	Pr(X = k)
250000	0.00000257
5000	0.000003337
250	0.000037220
100	0.000483653
20	0.001041124
10	0.013368984
10	0.009293680
5	0.029585799
0	0.946185946
	1.000000000
	$\begin{array}{r} 250000\\ 5000\\ 250\\ 100\\ 20\\ 10\\ 10\\ 10\\ \end{array}$

Suggested Exercises: Q18–26.