





Scatterin

Motivation

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F. Relate $\pi_a/s_{\widetilde{a}}$ to scatter-equivalence classes ("lines if there is a chain $a = b_0, b_1, \ldots, b_n = c$ with $\omega_{b_{m-1},\widetilde{b}_m} > 0$, then $\pi_a/s_{\widetilde{a}} = \pi_c/s_{\widetilde{c}}$.

RRF

Warwick Statistics

References

Statistics

Motivation

Motivation

Scattering - an abstract approach (III)

Scattering

- 5 Adopt "Metropolis-Hastings recipe": divide state-space into equivalence classes using ω ,
 - set $\pi_a = \min{\{\kappa, \kappa'\}}$ where we choose κ , κ' as positive constants belonging to classes of a and \tilde{a} ,
 - set scattering probability $s_a = \min\{1, \kappa/\kappa'\}$ (dynamic reversibility is then automatic!).
- 6 In case of a suitable total ordering ≺ for each "line", transmission probabilities are functions of scattering probabilities.

For each $a \prec b$, there are $\omega_{a,\pm}$ summing to 1 with

$$p_{a,\widetilde{b}} = \omega_{a,\widetilde{b}} s_{\widetilde{b}} = \omega_{a,+} \left(\prod_{a \prec c \prec b} (1 - s_{\widetilde{c}}) \right) s_{\widetilde{b}},$$

and similar for $p_{b,\tilde{a}}$ using $\omega_{b,-}$.

All follows from choice of the class constants κ (and say equiprobable choice of direction $\omega_{a,\pm} = \frac{1}{2}$).

Application

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Define the SIRSN-RRF, sampled at changes in direction, by specifying equilibrium probabilities at intersections of lines.

- 1. Scaling invariance: $\pi_{(\ell_1,\ell_2)} = \min\{v_1^{\alpha}, v_2^{\alpha}\}$, parameter α .
- 2. Scattering probability: $s_{(\ell_1,\ell_2)} = \min\{1, (\nu_2/\nu_1)^{\alpha}\}.$
- 3. Dynamical reversibility: non-symmetric Dirichlet form.
- 4. Apply Campbell-Slivnyak-Mecke theorem (twice!) to identify (translated, rotated, scaled) "environment viewed from particle" *via* reduced non-symmetric Dirichlet form.
- 5. Resulting log-relative-speed-changes X_1, X_2, \ldots form a stationary process.

Dynamical reversibility

Let $f(x,\Pi)$ be bounded, measurable, x an intersection of lines \mathcal{L}_1 , \mathcal{L}_2 in Π . For convenience set $\widetilde{f}(\mathcal{L}_1, \mathcal{L}_2; \Pi) = f(\mathcal{L}_2, \mathcal{L}_1; \Pi)$. Consider the non-symmetric form

$$B(f,g) = \mathbb{E}\left[\mathbb{E}\left[\mathbb{E}\left[\mathbb{E}\left[\sum_{\mathcal{L}_{1}\neq\mathcal{L}_{2}\in\Pi}\widetilde{f}(\widetilde{Z}_{0};\Pi)\times g(Z_{1};\Pi)\times \pi_{x} \mid Z_{0}=x=(\mathcal{L}_{1},\mathcal{L}_{2})\right] \mid \Pi\right]\right].$$

Using Campbell-Mecke-Slivnyak theory twice, this can be reduced (taking out translations, rotations, scale-changes) to the study of

$$\mathbb{E}\Big[\sum_{\mathcal{L}_{3}\in\Pi}f^{(2)}(\mathcal{L}_{1}^{*};\Pi\cup\{\mathcal{L}_{1}^{*}\})s_{(\tilde{\mathcal{L}}_{0},\mathcal{L}_{1}^{*})}\left(\prod_{\mathcal{L}\in\Pi:\ \mathcal{L} \text{ separates origin from }\tilde{\mathcal{L}}_{0}\cap\mathcal{L}_{3}}(1-s_{(\tilde{\mathcal{L}}_{0},\mathcal{L})})\right)\times s_{(\tilde{\mathcal{L}}_{0},\mathcal{L}_{3}}g^{(2)}(\mathcal{L}_{3};\Pi\cup\{\mathcal{L}_{1}^{*}\})\Big]$$

Read off equilibrium distribution from reduced non-symmetric form: at critical $\alpha = 2(\gamma - 1)$, typical log-relative-speed-change *X* has stationary symmetric Laplace distribution.

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| Outline of remainder of argument | Conclusion |
| Adapt Kozlov (1985, Section 2) to show X is ergodic (depends on nice properties of Poisson line process!). Critical case E [X] = 0, i.e. α = 2(γ − 1): apply continuum adaptation of Kesten-Spitzer-Whitman range theorem (Spitzer, 1976, Page 38) to show log-speed process ∑X is neighbourhood recurrent. In this critical case α = 2(γ − 1), SIRSN-RRF provides a "randomly-broken Π-geodesic" which avoids slowing down to zero speed (or speeding up to infinite speed). | Critical case (α = 2(γ - 1)): SIRSN-RRF speed is neighbourhood-recurrent. Sub-critical case (α < 2(γ - 1)): SIRSN-RRF converges to a random limiting point in the plane (trapped by cells of tessellation of high-speed lines). Super-critical case (α > 2(γ - 1)): SIRSN-RRF disappears off to infinity (consider high-speed tessellation). So a critical "randomly-broken Π-geodesic" does not halt <i>en route</i>. What about Π-geodesics themselves? |
| Warwick Statistics | THANK YOU! |
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