# Exact Bayesian Inference (for Big Data) 

Single- and Multi- Core Approaches

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## Cartoon



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■ Algorithmic ‘Scalability’

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■ Multi-Core

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Vetropolis move from $\theta \rightarrow \phi$ is accepted w.p.

- Goal: Scalability of iterative cost.
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1 Break data into $S$ 'shards' (of size N/S)
2 Separate inferences [MCMC]

- 'Recombine' on 'mother-core
- Problem: Recombining - How do you do it?

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[2] Bayesian Fusion: An exact and parallelisable consensus approach to unifyina distributed analyses


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## 0 - Retrospective Trust / Tricks

## Brownian Motion



## Brownian Motion



Time

## Path-space Rejection Sampling

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■ We want $X \sim \mathbb{Q}$ where:

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\mathbb{Q}: \mathrm{d} X_{t}=\alpha\left(X_{t}\right) \mathrm{d} t+\Lambda^{1 / 2} \mathrm{~d} B_{t}, \quad X_{0}=x \in \mathbb{R}^{d}, t \in[0, T]
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■ Discretisation Free Approach!: Path-space Rejection Sampler (PRS) (see arXiv 1302.6964 for details)
$1 X_{T} \sim h_{T}\left(X_{0}\right)$
$2 X^{\text {tin }} \sim \mathbb{P} \mid X_{T^{*}}($ eg $\mathbb{W}$ or $\mathbb{C})$
3 (Accept / Reject)** / Assign Weight**

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■ If $X_{0} \sim v$, then $\forall t>0, X_{t} \sim v$

## 1 - Single Core: Quasi-Stationary Monte Carlo

## Quasi-Stationary Monte Carlo

■ Consider Brownian motion, killed at $\tau$ with intensity

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- Implementation? $\rightarrow$ ScaLE


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- We require control variates for good scaling of $\tilde{K} / K \ldots$ (omitted)


## 1.3 - Single-Core: ScaLE

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- Continuous time multi-level splitting / Importance sampling QSMC + SMC + Resampling


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## 1.4 - Summary

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■ Summary...:

- QSMC: 'Exact' Bayesian Inference
- No intrinsic cost for exactness.
- ScaLE's well!
- Missing Bits.
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■ Theory: QSMC; (SMC-) ScaLE; Re-ScaLE.

- Scaling: Dimensionality; Control-Variate...

■ Implementational Details

## Example

## $2^{27}$ dataset, contaminated regression model



## 2 - Multi-Core: Bayesian Fusion

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■ $\mathbb{L}_{1}, \ldots, \mathbb{L}_{C}, \mathbb{D}_{1}, \ldots, \mathbb{D}_{C} \ldots$

## Fusion Idea



## Fusion Actual



## Some Details

■ Fusion Measure ( $\mathfrak{X} \in \boldsymbol{\Omega}_{\mathbf{0}}$ )

$$
\mathrm{dF}(\mathfrak{X}) \propto \mathrm{d}\left(\times_{c=1}^{c} \mathbb{D}_{c}^{\boldsymbol{X}_{0}^{(c)}, \boldsymbol{y}_{T}}\right)(\mathfrak{X}) \cdot \prod_{c=1}^{c}\left[f_{c}^{2}\left(\boldsymbol{X}_{0}^{(c)}\right) p_{T, c}^{\mathrm{dl}}\left(\boldsymbol{y}_{T} \mid \boldsymbol{X}_{0}^{(c)}\right) \cdot \frac{1}{f_{c}\left(\boldsymbol{y}_{T}\right)}\right],
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■ Key Idea: If $\mathfrak{X} \sim \mathbb{F}$, then $\mathfrak{X}_{T} \sim \prod_{c=1}^{C} f_{c} \propto \pi(!)$

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■ 'Brownian':

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\operatorname{dP} \mathbb{P}^{\mathrm{bm}}(\mathfrak{X}) \propto \mathrm{d}\left(\times_{c=1}^{C} \mathbb{W}_{c}^{\boldsymbol{X}_{0}^{(c)}, \boldsymbol{y}_{T}}\right)(\mathfrak{X}) \cdot h_{T}^{\mathrm{bm}}\left(\boldsymbol{X}_{0}^{(1: C)}, \boldsymbol{y}_{T}\right), \mathfrak{X} \in \boldsymbol{\Omega}_{0}
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## Some Details

■ Simple ‘Brownian’ Case:


- Exact ('Talking') vs. Approximate ('Silent' / 'Lecture') Fusion


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- 'Optimal' $h_{T}^{\text {bm }}(\cdot, \cdot)$ :

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- Need RS for $h_{T}^{\mathrm{bm}}(\cdot, \cdot)$ end point.
- Accept with probability

$$
P(\mathfrak{X}):=\exp \left[-\sum_{c=1}^{c} \int_{0}^{T} \kappa_{c}\left(\boldsymbol{X}_{t}^{(c)}\right) \mathrm{d} t\right] \in[0,1]
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- 'Optimal' $h_{T}^{\mathrm{bm}}(\cdot, \cdot)$ :

$$
h_{T}^{\mathrm{bm}}\left(\boldsymbol{X}_{0}^{(1: C)}, \boldsymbol{y}_{T}\right) \propto \underbrace{\left[\prod_{c=1}^{C} f_{c}\left(\boldsymbol{X}_{0}^{(c)}\right)\right]}_{\text {initial core draws }} \underbrace{\exp \left(-\frac{C \cdot\left\|\boldsymbol{y}_{T}-\overline{\boldsymbol{X}}_{0}\right\|^{2}}{2 T}\right) \cdot \exp \left(-\frac{C \sigma^{2}}{2 T}\right)}_{\text {end point draw }}
$$

- Need RS for $h_{T}^{\text {bm }}(\cdot, \cdot)$ end point.
- Accept with probability

$$
P(\mathfrak{X}):=\exp \left[-\sum_{c=1}^{c} \int_{0}^{T} \kappa_{c}\left(\boldsymbol{X}_{t}^{(c)}\right) \mathrm{d} t\right] \in[0,1]
$$

■ Exact ('Talking’) vs. Approximate ('Silent' / 'Lecture’) Fusion

## Some Details

■ Simple ‘Brownian’ Case:

- 'Optimal' $h_{T}^{\mathrm{bm}}(\cdot, \cdot)$ :

$$
h_{T}^{\mathrm{bm}}\left(\boldsymbol{X}_{0}^{(1: C)}, \boldsymbol{y}_{T}\right) \propto \underbrace{\left[\prod_{c=1}^{C} f_{c}\left(\boldsymbol{X}_{0}^{(c)}\right)\right]}_{\text {initial core draws }} \underbrace{\exp \left(-\frac{C \cdot\left\|\boldsymbol{y}_{T}-\overline{\boldsymbol{X}}_{0}\right\|^{2}}{2 T}\right) \cdot \exp \left(-\frac{C \sigma^{2}}{2 T}\right)}_{\text {end point draw }}
$$

- Need RS for $h_{T}^{\mathrm{bm}}(\cdot, \cdot)$ end point.
- Accept with probability

$$
P(\mathfrak{X}):=\exp \left[-\sum_{c=1}^{c} \int_{0}^{T} \kappa_{c}\left(\boldsymbol{X}_{t}^{(c)}\right) \mathrm{d} t\right] \in[0,1]
$$

■ Exact ('Talking') vs. Approximate ('Silent' / 'Lecture') Fusion
■ Remark: ‘Ornstein-Uhlenbeck’ special case

## Some Details



## Example

## Beta(5,5) density



## Questions?

