# Parabolic estimates and Poisson process

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# Introduction

- 1. As a first result we show that from Schauder or Sobolev-space estimates for the one-dimensional heat equation one gets their multidimensional analogs for equations with time-dependent coefficients with the *same* constants as in the case of the one-dimensional heat equation.
- 2. In particular constants in the parabolic estimates do not depend on the dimension.
- 3. The method is quite general and is based on using the Poisson stochastic process.
- 4. We can also treat equations involving non-local operators and other class of equations and systems.
- 5. It seems to be a challenging problem to find a purely analytic approach to proving such results.
- 6. I will only mention some general results of paper. Rather I will try to show how the method works and the basic idea.

# Some function spaces

 $C^{\alpha}(\mathbb{R}^d)$ ,  $\alpha \in (0, 1)$ , is the space of all  $f : \mathbb{R}^d \to \mathbb{R}$  for which the following norm

$$\|f\|_{C^{\alpha}(\mathbb{R}^d)} = \sup_{x \in \mathbb{R}^d} |f(x)| + [f]_{C^{\alpha}(\mathbb{R}^d)}$$

is finite, where  $[f]_{C^{\alpha}(\mathbb{R}^d)} = \sup_{x \neq y} \frac{|f(x) - f(y)|}{|x-y|^{\alpha}}$ .

By  $C^{2+\alpha}(\mathbb{R}^d)$  we mean the space of real-valued twice continuously differentiable functions f on  $\mathbb{R}^d$  having finite norm

$$\|f\|_{C^{2+\alpha}(\mathbb{R}^d)} = \sup_{x \in \mathbb{R}^d} (|f(x)| + |Df(x)| + |D^2f(x)|) + [D^2f]_{C^{\alpha}(\mathbb{R}^d)},$$

where Df is the gradient of f and  $D^2f$  is its Hessian.

For a real-valued function f(t, x),  $t \in (0, T)$ ,  $x \in \mathbb{R}^d$ , write

 $f \in B_c((0,T), C_0^{\infty}(\mathbb{R}^d))$ 

if *f* is a Borel bounded function, such that  $f(t, \cdot) \in C_0^{\infty}(\mathbb{R}^d)$  for any  $t \in (0, T)$ ; for any n = 0, 1, ..., the  $C^n(\mathbb{R}^d)$ -norms of  $f(t, \cdot)$  are bounded on (0, T), and the supports of  $f(t, \cdot)$  belong to the same ball.

## Parabolic estimates for the one dimensional heat equation

$$\partial_t u(t,x) = D^2 u(t,x) + f(t,x), \qquad u(0,\cdot) = 0$$

(1)

for  $t \in (0, T)$ ,  $x \in \mathbb{R}$ . We treat the problem in the integral form:

$$u(t,x) = \int_0^t (D^2 u(s,x) + f(s,x)) ds, \ t \in [0,T], \ x \in \mathbb{R}.$$

Fix  $\alpha \in (0, 1)$  and  $p \in (1, \infty)$ . One knows (see for instance Ladyzhenskaya-Solonnikov-Uraltseva 1968):

if  $f \in B_c((0,T), C_0^{\infty}(\mathbb{R}))$ , then there is a unique solution u(t,x) such that u is continuous in  $[0,T] \times \mathbb{R}$ ;  $u(t, \cdot) \in C^{2+\alpha}(\mathbb{R})$ , for any  $t \in [0,T]$ , and

$$\sup_{t\in[0,T]}\|u(t,\cdot)\|_{C^{2+\alpha}(\mathbb{R})}\leqslant N_0(T,\alpha)\sup_{t\in(0,T)}\|f(t,\cdot)\|_{C^{\alpha}(\mathbb{R})},$$

furthermore:

$$\sup_{\substack{(t,x)\in[0,T]\times\mathbb{R}\\\in[0,T]}} |u(t,x)| \leqslant T \sup_{\substack{(t,x)\in(0,T)\times\mathbb{R}\\t\in(0,T]}} |f(t,x)|,$$
(2)  
$$\sup_{\substack{\in[0,T]\\\mathbb{L}^{2}u(t,\cdot)]_{C^{\alpha}(\mathbb{R})}} \leqslant N_{0}(\alpha) \sup_{\substack{t\in(0,T)\\t\in(0,T)}} |f(t,\cdot)]_{C^{\alpha}(\mathbb{R})},$$
(3)  
$$\|D^{2}u\|_{L_{p}((0,T)\times\mathbb{R})}^{p} \leqslant N_{p}\|f\|_{L_{p}((0,T)\times\mathbb{R})}^{p},$$
(4)

where  $L_p$ -spaces are defined with respect to Lebesgue measure and  $N_0(\alpha)$ ,  $N_p$  are some constants. The previous (2), (3) and (4) are *parabolic estimates*.

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# I Theorem in [Krylov, P.]

Let  $a(t) = (a^{ij}(t))$  be a  $d \times d$  symmetric matrix-valued locally bounded Borel measurable function on (0, T) such that

 $a^{ij}(t)\lambda^i\lambda^j \geqslant |\lambda|^2, \quad t \in (0,T), \ \lambda \in \mathbb{R}^d.$ 

For any  $f \in B_c((0, T), C_0^{\infty}(\mathbb{R}^d))$  there exists a unique continuous in  $[0, T] \times \mathbb{R}^d$  solution u(t, x) of the equation

 $\partial_t u(t,x) = a^{ij}(t)D_{ij}u(t,x) + f(t,x), \quad u(0,\cdot) = 0$ 

in  $(0, T) \times \mathbb{R}^d$  such that, for any  $t \in [0, T]$ ,  $u(t, \cdot) \in C^{2+\alpha}(\mathbb{R}^d)$  and, for any i, j = 1, ..., d and unit vector  $l \in \mathbb{R}^d$ , we have:

 $\sup_{(t,x)\in[0,T]\times\mathbb{R}^d} |u(t,x)| \leqslant T \sup_{(t,x)\in(0,T)\times\mathbb{R}^d} |f(t,x)| \quad \text{(Max. Principle),}$ 

$$\sup_{t\in[0,T]} [D_{ij}u(t,\cdot)]_{C^{\alpha}(\mathbb{R}^{d})} \leqslant N'(\alpha)N_{0}(\alpha) \sup_{t\in(0,T)} [f(t,\cdot)]_{C^{\alpha}(\mathbb{R}^{d})},$$
(5)

 $\sup_{(t,x)\in[0,T]\times\mathbb{R}^d} [D_l^2 u(t,x+l\cdot)]_{C^{\alpha}(\mathbb{R})} \leqslant N_0(\alpha) \sup_{(t,x)\in(0,T)\times\mathbb{R}^d} [f(t,x+l\cdot)]_{C^{\alpha}(\mathbb{R})},$ (6)

$$\|D_{l}^{2}u\|_{L_{p}((0,T)\times\mathbb{R}^{d})}^{p} \leqslant N_{p}\|f\|_{L_{p}((0,T)\times\mathbb{R}^{d})}^{p},$$
(7)

where  $N_0(\alpha)$ ,  $N_p$  are the previous one-dimensional constants.

# Idea of proof when $a^{ij}(t) = \delta_{ij}$

We are considering in  $(0, T) \times \mathbb{R}^d$ :

$$\partial_t v(t,x) = \Delta v(t,x) + f(t,x), \quad u(0,\cdot) = 0 \tag{8}$$

and show that parabolic estimates hold true with the same one-dimensional constants.

No analytic methods are available up to now.

We use the Poisson process and random PDEs

Take a sequence  $\tau_1 = \tau_1(\omega)$ ,  $\tau_2 = \tau_2(\omega)$ , ... of independent random variables defined on a probability space  $(\Omega, \mathcal{F}, P)$  with common exponential distribution with parameter  $\lambda > 0$ , so that  $P(\tau_n > t) = e^{-\lambda t}$  for  $t \ge 0$  and n = 1, 2..... Define

$$\sigma_0 = 0, \quad \sigma_n = \sum_{i=1}^n \tau_i, \quad n = 1, 2, ..., \quad \pi_t = \pi_t(\omega) = \sum_{n=1}^\infty I_{\sigma_n \leq t}$$

(where  $I_{\sigma_n \leq t}$  denotes the indicator function of the event { $\sigma_n \leq t$ }). We see that  $\pi_t$  is the number of consecutive sums of  $\tau_i$  which lie on [0, *t*].

The counting process  $\pi_t$  is known as a Poisson process with parameter  $\lambda$ .

The Poisson process

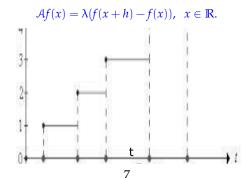
For  $0 \leq s \leq t < \infty$  and k = 0, 1, ... it holds that

$$P(\pi_t - \pi_s = k) = \frac{[\lambda(t-s)]^k}{k!} e^{-\lambda(t-s)},$$

 $\lambda > 0$  and moreover, for any  $t > s \ge 0$ ,  $\pi_t - \pi_s$  is independent of the  $\sigma$ -algebra generated by all  $\pi_r$ , when  $r \in [0, s]$ .

Let  $\pi_{s-} = \lim_{t \uparrow s} \pi_t$ , s > 0.

Let  $h \in \mathbb{R}$ . We do first some elementary computations related to the generator of  $h\pi_t$  (below in the picture h = 1):



#### Generator of $h\pi_t$ with parameter $\lambda > 0$

Let  $u_0 \in C_b(\mathbb{R})$  be a bounded continuous function. Let  $\omega \in \Omega$  such that  $n = \pi_t(\omega)$ . We have, for  $x \in \mathbb{R}$ , t > 0, omitting  $\omega$ ,

$$\begin{split} u_0(x+h\pi_t) - u_0(x) \\ = u_0(x+h\pi_{\sigma_{n-}}+h) - u_0(x+h\pi_{\sigma_{n-}}) + u_0(x+h\pi_{\sigma_{n-1-}}+h) - u_0(x+h\pi_{\sigma_{n-1-}}) \\ \dots + u_0(x+h\pi_{\sigma_{1-}}+h) - u_0(x+h\pi_{\sigma_{1-}}) \\ = \sum_{k=1}^n \left( u_0(x+h\pi_{\sigma_{k-}}+h) - u_0(x+h\pi_{\sigma_{k-}}) \right) \\ = \sum_{\sigma_k \leqslant t} \int_0^t \left( u_0(x+h\pi_{s-}+h) - u_0(x+h\pi_{s-}) \right) \delta_{\sigma_k}(ds) \\ = \int_0^t \left( u_0(x+h\pi_{s-}+h) - u_0(x+h\pi_{s-}) \right) d\pi_s \quad \text{(Lebesgue-Stieltjes integral)}. \end{split}$$

Applying expectation:

$$E\left[\int_{0}^{t} \left(u_{0}(x+h\pi_{s-}+h)-u_{0}(x+h\pi_{s-})\right)d\pi_{s}\right] = \lambda \int_{0}^{t} E\left[u_{0}(x+h\pi_{s}+h)-u_{0}(x+h\pi_{s})\right]ds$$

Set  $v_t(x) = v(t, x) = E[u_t(x + h\pi_t)]$ . Then

$$v_t(x) - u_0(x) = \lambda \int_0^t \left[ v_s(x+h) - v_s(x) \right] ds,$$

i.e.,  $\partial_t v_t(x) = \lambda(v_t(x+h) - v_t(x))$ 

The proof for  $\partial_t v(t, x) = \Delta v(t, x) + f(t, x)$  in  $(0, T) \times \mathbb{R}^d$ 

We consider d = 2. The general case comes from induction. Thus we need to pass from parabolic estimates with d = 1 to estimates with d = 2.

**I step.** Take a function f(t, x, y) in  $B_c((0, T), C_0^{\infty}(\mathbb{R}^2))$  and for each  $\omega \in \Omega$  and  $y \in \mathbb{R}$  solve:

$$\partial_t u(t, x, y, \omega) = D_x^2 u(t, x, y, \omega) + f(t, x, y - h\pi_t(\omega))$$
(9)

with zero initial data, where  $h \in \mathbb{R}$  is a parameter. We often do not indicate the dependence on  $\omega$ . Moreover, we also drop the dependence on h.

There exists a unique solution u(t, x, y), depending on y, h and  $\omega$  as parameters, such that main estimates (2), (3), and (4) hold for each  $\omega$ , h and  $y \in \mathbb{R}$  with the same constants if we replace u(t, x) and f(t, x) with u(t, x, y) and  $f(t, x, y - h\pi_t)$ , respectively.

Furthermore, since  $f \in B_c((0, T), C_0^{\infty}(\mathbb{R}^2))$ , one can prove that u(t, x, y) is uniformly continuous with respect to y uniformly with respect to  $\omega$ , t, h, and x

Let us see what equation is verified by

 $u(t, x, y + h\pi_t)$ 

By considering  $u(t, x, y + h\pi_t)$  on each interval  $[\sigma_n, \sigma_{n+1})$  on which  $h\pi_t$  is constant, one easily derives that

$$u(t, x, y + h\pi_t) = \int_0^t [D_x^2 u(s, x, y + h\pi_s) + f(s, x, y)] \, ds + \int_{(0,t]} g(s, x, y) \, d\pi_s \quad (10)$$
$$= \int_0^t [D_x^2 u(s, x, y + h\pi_s) + f(s, x, y)] \, ds + \sum_{\sigma_n \leq t} g(\sigma_n, x, y),$$

where

$$g(s, x, y) = u(s, x, y + h + h\pi_{s-}) - u(s, x, y + h\pi_{s-})$$
(11)

is the jump of  $u(t, x, y + h\pi_t)$  as a function of *t* at moment *s* if  $\pi_t$  has a jump at *s*.

Recall  $\pi_{s-} = \lim_{t\uparrow s} \pi_t$ , s > 0. For instance, if  $t \in [\sigma_1, \sigma_2)$  we have

$$u(t, x, y + h\pi_t) = u(t, x, y + h) = \int_{\sigma_1}^t [D_x^2 u(s, x, y + h) + f(s, x, y)] ds$$
  
+  $u(\sigma_1, x, y + h) - u(\sigma_1, x, y) + \int_0^{\sigma_1} [D_x^2 u(s, x, y) + f(s, x, y)] ds.$ 

Let

 $v(t, x, y) := E[u(t, x, y + h\pi_t)].$ 

We get, for any  $t \in (0, T)$ ,  $x, y \in \mathbb{R}$ ,

$$v(t, x, y) = \int_0^t \left( D_x^2 v(s, x, y) + \lambda [v(s, x, y + h) - v(s, x, y)] + f(s, x, y) \right) ds.$$

**II step.** Let  $f \in B_c((0,T), C_0^{\infty}(\mathbb{R}^2))$ ,  $h \in \mathbb{R}$  and  $\lambda > 0$ . Then there exists a unique bounded continuous function v(t, x, y),  $t \in [0, T]$ ,  $x, y \in \mathbb{R}$ , satisfying

$$\partial_t v(t, x, y) = D_x^2 v(t, x, y) + \lambda [v(t, x, y+h) - v(t, x, y)] + f(t, x, y)$$
(12)

for  $t \in (0, T)$ ,  $x, y \in \mathbb{R}$ , with zero initial condition and such that  $v(t, \cdot, y) \in C^{2+\alpha}(\mathbb{R})$ for any  $t \in (0, T)$ ,  $y \in \mathbb{R}$  and

$$\sup_{(t,y)\in[0,T]\times\mathbb{R}}\|v(t,\cdot,y)\|_{C^{2+\alpha}(\mathbb{R})}\leqslant N_0(T,\alpha)\sup_{(t,y)\in(0,T)\times\mathbb{R}}\|f(t,\cdot,y)\|_{C^{\alpha}(\mathbb{R})}.$$

*Furthermore with*  $N_0(\alpha)$  *and*  $N_p$  *as in* (3) *and* (4)*:* 

$$\sup_{\substack{(t,z)\in[0,T]\times\mathbb{R}^{2}\\(t,y)\in[0,T]\times\mathbb{R}}} |v(t,z)| \leqslant T \sup_{\substack{(t,z)\in(0,T)\times\mathbb{R}^{2}\\(t,y)\in(0,T)\times\mathbb{R}}} |f(t,z)|,$$

$$\sup_{\substack{(t,y)\in(0,T)\times\mathbb{R}\\}} [D_{x}^{2}v(t,\cdot,y)]_{C^{\alpha}(\mathbb{R})} \leqslant N_{0}(\alpha) \sup_{\substack{(t,y)\in(0,T)\times\mathbb{R}\\(t,y)\in(0,T)\times\mathbb{R}^{2}\\(t,y)\in(0,T)\times\mathbb{R}^{2}\\(t,y)\in(0,T)\times\mathbb{R}^{2}\\(t,y)\in(0,T)\times\mathbb{R}^{2}} [f(t,z)],$$
(13)

Recall that by uniqueness  $v(t, x, y) := E[u(t, x, y + h\pi_t)].$ 

Let us only check

$$||D_x^2 v||_{L_p((0,T)\times\mathbb{R}^2)}^p \leq N_p ||f||_{L_p((0,T)\times\mathbb{R}^2)}^p.$$

We compute, using also Jensen inequality and the Fubini theorem,

$$\begin{split} \|D_x^2 v\|_{L_p}^p &= \int_{[0,T] \times \mathbb{R}^2} \left| E \Big[ D_x^2 u(t,x,y+h\pi_t) \Big] |^p dt dx dy \\ &\leqslant \int_0^T dt \int_{\mathbb{R}^2} E \Big[ |D_x^2 u(t,x,y+h\pi_t)|^p \Big] dx dy \\ &= \int_0^T dt \int_{\mathbb{R}^2} E \Big[ |D_x^2 u(t,x,z|^p) \Big] dx dz \\ &= \int_{\mathbb{R}} dz \int_0^T dt \int_{\mathbb{R}} E \Big[ |D_x^2 u(t,x,z|^p) \Big] dx dz \\ &\leqslant N_p \int_{\mathbb{R}} dz \int_0^T dt \int_{\mathbb{R}} |f(t,x,z|^p) dx. \end{split}$$

We have also used invariance by translation of the Lebesgue measure.

**III step.** By repeating the above argument, we see that

 $w(t, x, y) := Ev(t, x, y - h\pi_t)$ 

satisfies

$$\partial_t w(t, x, y) = D_x^2 w(t, x, y) + \lambda [w(t, x, y + h) - 2w(t, x, y) + w(t, x, y - h)] + f(t, x, y)$$
(14)

and admits the same parabolic estimates as before (with the same constants)

#### Then we take $\lambda = h^{-2}$ in (13) and let $h \downarrow 0$ .

By using Ascoli-Arzela, one can show that the solutions  $w = w_h$  of (13) with  $\lambda = h^{-2}$  converge to a function v(t, x, y), that is infinitely differentiable with respect to (x, y) for any t with any derivative continuous and bounded on  $[0, T] \times \mathbb{R}^2$ , (equals zero for t = 0); it satisfies

$$\partial_t v(t, x, y) = \Delta_{xy} v(t, x, y) + f(t, x, y)$$
(15)

in  $(0, T) \times \mathbb{R}^2$  and for which all the parabolic estimates hold true with the same constants.

Bounded continuous in  $[0, T] \times \mathbb{R}^2$  solutions of (14) having continuous second-order derivatives with respect to (x, y) and vanishing at t = 0 are unique, and we get that, for any such solution the previous parabolic estimates hold true with the same constants.

**IV step.** Take a unit vector  $l_1 \in \mathbb{R}^2$  and a unit vector  $l_2 \in \mathbb{R}^2$  orthogonal to  $l_1$ . Let *S* be an orthogonal transformation of  $\mathbb{R}^2$  such that  $Se_i = l_i$ , i = 1, 2, where  $e_1, e_2$  is the standard basis in  $\mathbb{R}^2$ , and set  $f(t, xe_1 + ye_2) = f(t, x, y)$ ,  $v(t, xe_1 + ye_2) = v(t, x, y)$ ,

 $S(x,y) = xl_1 + yl_2, \quad g(t,x,y) = f(t,S(x,y)), \quad w(t,x,y) = v(t,S(x,y)).$ 

Since the Laplacian is rotation invariant, we have

 $\partial_t w(t, x, y) = \Delta w(t, x, y) + g(t, x, y)$ 

and, since g is as regular as f, we conclude by defining

$$K = \sup_{(t,y)\in(0,T)\times\mathbb{R}} \sup_{x_1,x_2\in\mathbb{R}, x_1\neq x_2} \frac{|g(t,x_1,y) - g(t,x_2,y)|}{|x_1 - x_2|^{\alpha}}$$

that

$$\sup_{(t,y)\in[0,T]\times\mathbb{R}} \sup_{x_1\neq x_2} \frac{|D_x^2 w(t,x_1,y) - D_x^2 w(t,x_2,y)|}{|x_1 - x_2|^{\alpha}} \leqslant N_0(\alpha) K.$$
(16)

Observe that

$$D_x^2 w(t, x, y) = (D_{l_1}^2 v)(t, S(x, y)) = (D_{l_1}^2 v)(t, xl_1 + yl_2),$$

where  $D_l^2 = l^i l^j D_{ij}$  and  $D_i = \partial/\partial x^i$ ,  $D_{ij} = D_i D_j$ .

Therefore, the left-hand side of (15) equals

$$\begin{split} \sup_{(t,y)\in[0,T]\times\mathbb{R}} \sup_{x,\nu,\mu\in\mathbb{R},\mu\neq\nu} \frac{|D_{l_1}^2v(t,\mu l_1+xl_1+yl_2) - D_{l_1}^2v(t,\nu l_1+xl_1+yl_2)|}{|\mu-\nu|^{\alpha}} \\ &= \sup_{(t,z)\in[0,T]\times\mathbb{R}^2} \sup_{\mu\neq\nu} \frac{|D_{l_1}^2v(t,\mu l_1+z) - D_{l_1}^2v(t,\nu l_1+z)|}{|\mu-\nu|^{\alpha}}. \end{split}$$

Similarly the right-hand side of (15) is transformed and we get that for the bounded continuous in  $[0, T] \times \mathbb{R}^2$  solution v of (14) having continuous second-order derivatives with respect to (x, y) and vanishing at t = 0 and any unit vector  $l \in \mathbb{R}^2$ :

$$\begin{split} \sup_{(t,z)\in[0,T]\times\mathbb{R}^2} & \sup_{\mu\neq\nu} \frac{|D_l^2 v(t,\mu l+z) - D_l^2 v(t,\nu l+z)|}{|\mu-\nu|^{\alpha}} \\ \leqslant N_0(\alpha) & \sup_{(t,z)\in(0,T)\times\mathbb{R}^2} & \sup_{\mu\neq\nu} \frac{|f(t,\mu l+z) - f(t,\nu l+z)|}{|\mu-\nu|^{\alpha}}. \end{split}$$

Since the Jacobian of the above S(x, y) equals one, for any unit vector  $l \in \mathbb{R}^2$ 

$$\int_0^T \int_{\mathbb{R}^2} |D_l^2 v(t,z)|^p \, dz dt \leqslant N_p \int_0^T \int_{\mathbb{R}^2} |f(t,z)|^p \, dz dt. \quad \Box$$

# A remark on the previous proof

We have considered  $w = w_h$ 

$$\partial_t w(t, x, y) = D_x^2 w(t, x, y) + \frac{1}{h^2} [w(t, x, y + h) - 2w(t, x, y) + w(t, x, y - h)] + f(t, x, y)$$
(17)

One can apply the finite-difference operators with respect to (x, y) of any order to (16); these operators are obtained by compositions of the **first order difference operators** like

$$\delta_{r,i}v(z) = r^{-1}[v(z+re_i)-v(z)], \quad i=1,2,$$

where  $e_i$  is the *i*th basis vector and r > 0.

By the Maximum Principle and the fact that any derivative of any order of *f* is in  $B_c((0, T), C_0^{\infty}(\mathbb{R}^2))$ , we conclude that any finite-difference of any order of  $w_h$  is bounded on  $\mathbb{R}^2$  uniformly with respect to *t* and *h*.

It follows that  $w_h$  is infinitely differentiable with respect to (x, y) and any derivative of any order is bounded on  $[0, T] \times \mathbb{R}^2$ .

Then equation (16) itself shows that these derivatives are Lipschitz continuous in *t*.

Thus, the family  $w_h$  is equi-Lipschitz in each compact set of  $[0, T] \times \mathbb{R}^2$  and the same holds for any derivative with respect to (x, y) of  $w_h$ .

We can apply the Arzelà-Ascoli theorem on  $[0, T] \times \{|(x, y)| \leq R\}, R \in (0, \infty)$ , along with any derivative with respect to (x, y) of  $w_{h_n}$  and  $\partial_t w_{h_n}$ .

Writing (16) in the integral form and passing to the limit as  $n \to \infty$ , we conclude that there exists a continuous function v(t, x, y) in  $[0, T] \times \mathbb{R}^2$ , which is infinitely differentiable with respect to (x, y) with any derivative bounded on  $[0, T] \times \mathbb{R}^2$ .

Hence, the equation

$$\partial_t u(t, x, y) = \Delta_{x, y} u(t, x, y) + f(t, x, y)$$

holds in integral form on  $(0, T) \times \mathbb{R}^2$ .

On the proof for  $\partial_t v(t, x) = Tr(a(t)D_x^2v(t, x)) + f(t, x)$ 

We have to solve

$$\partial_t v(t, x) = Tr(a(t)D_x^2 v(t, x)) + f(t, x), \quad v(0, \cdot) = 0 \text{ or}$$

$$\partial_t v(t,x) = \triangle v(t,x) + Tr(c(t)D_x^2 v(t,x)) + f(t,x), \quad \text{with } c(t) = a(t) - I$$

We start from

$$\partial_t v(t,x) = \triangle v(t,x) + f(t,x) \tag{18}$$

Let  $h \in \mathbb{R}$  and consider the unit vector  $e_1 \in \mathbb{R}^d$ . We define

$$b_t = \int_0^t \sqrt{c(r)} e_1 d\pi_r = \sum_{\sigma_k \leq t} \sqrt{c(\sigma_k)} e_1.$$

If we replace f(t, x) with  $f(t, x - hb_t)$ , for each  $\omega$ , in eq. (17), one derives that  $u(t, x + hb_t)$  satisfies

$$u(t, x + hb_t) = \int_0^t [\triangle u(s, x + hb_s) + f(s, x)] \, ds + \int_{(0,t]} g(s, x) \, d\pi_s,$$

where

$$g(s,x) := u(s,x+h\sqrt{c(s)}\,e_1+hb_{s-}) - u(s,x+hb_{s-}).$$

Let

$$v(t,x) = Eu(t,x+hb_t).$$

Then we arrive at

$$\partial_t v(t,x) = \triangle v(t,x) + \lambda [v(t,x+h\sqrt{c(t)}\,e_1) - v(t,x)] + f(t,x).$$

After that we solve

 $\partial_t w(t,x) = \triangle w(t,x) + \lambda [w(t,x+h\sqrt{c(t)}e_1) - w(t,x)] + f(t,x+hb_t)$ 

and repeating the previous arguments we conclude that for each h > 0 there exists a unique solution  $u_h(t, x)$  on  $[0, T] \times \mathbb{R}^d$  to

$$\begin{aligned} \partial_t u_h(t,x) &= \triangle u_h(t,x) + f(t,x) \\ &+ h^{-2} [u_h(t,x+h\sqrt{c(t)}\,e_1) - 2u_h(t,x) + u_h(t,x-h\sqrt{c(t)}\,e_1)] \end{aligned}$$

in  $(0, T) \times \mathbb{R}^d$  with zero initial condition and for which all estimates claimed in the theorem hold true. Passing to the limit as before we get

$$\partial_t w(t,x) = \bigtriangleup w(t,x) + \langle D^2 w(t,x) \sqrt{c(t)} e_1, \sqrt{c(t)} e_1 \rangle$$

By adding other terms we arrive at

$$\partial_t w(t,x) = \triangle w(t,x) + \sum_{k=1}^d \langle D^2 w(t,x) \sqrt{c(t)} e_k, \sqrt{c(t)} e_k \rangle \quad \Box$$
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### An example from [Krylov-P.]

Let d = 2,  $\alpha \in (0, 1)$ , and  $L_t = \Delta$ . We know that for any

 $f \in B_c((0,T), C_0^\infty(\mathbb{R}^2))$ 

the equation (we write  $f(t, x) = f_t(x)$ )

$$u_t(x) = \int_0^t [\Delta u_s(x) + f_s(x)] \, ds, \quad t \leq T, x \in \mathbb{R}^2,$$

has a unique continuous solution such that

$$\sup_{\substack{(t,x)\in[0,T]\times\mathbb{R}^{2}}}|u_{t}(x)| + \sup_{t\in[0,T]}\int_{\mathbb{R}^{2}}|u_{t}(x)|\,dx$$

$$\leqslant N_{0}\bigg[\int_{0}^{T}\int_{\mathbb{R}^{2}}|f_{t}(x)|\,dxdt + \sup_{\substack{(t,x)\in[0,T]\times\mathbb{R}^{2}}}|f_{t}(x)|\bigg], \qquad (19)$$

$$\sup_{t\in[0,T]}[D_{l}^{2}u_{t}]_{C^{\alpha}(\mathbb{R}^{2})}\leqslant N_{\alpha}\sup_{t\in[0,T]}[f_{t}]_{C^{\alpha}(\mathbb{R}^{2})},\,\forall l:|l|=1, \qquad (20)$$

where  $N_0$  and  $N_{\alpha}$  are some constants.

We can prove that the equation

$$u_t(x) = \int_0^t [\Delta u_s(x) + M u_s(x) + f_s(x)] \, ds,$$

where

$$M\phi(x) = (x^2)^2 D_{11}\phi(x) - 2x^1 x^2 D_{12}\phi(x) + (x^1)^2 D_{22}\phi(x)$$
(21)  
$$-x^1 D_1\phi(x) - x^2 D_2\phi(x)$$

has a continuous solution, which satisfies estimates (18) and (19) (with the same  $N_0$  and  $N_{\alpha}$ ).

It seems that this is an unexpected new result.

# Some references

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## The general results

Let *W* be a set consisting of real-valued (Borel) measurable functions  $u = u_t = u_t(x) = u(t, x)$  on  $[0, T] \times \mathbb{R}^d$ .

Let  $\mathcal{G}$  be a commutative group of affine volume-preserving transformations of  $\mathbb{R}^d$ . If  $g, h \in \mathcal{G}$  by gh we mean the composition of the two transformations.

If f(x) is a function on  $\mathbb{R}^d$  and  $g \in \mathcal{G}$ , we define (gf)(x) = f(gx), where gx is the image of x under mapping g.

By  $B((0, T), \mathcal{G})$  we denote the set of bounded measurable  $\mathcal{G}$ -valued functions on (0, T),  $B(\mathbb{R}^d)$  is the set of Borel bounded functions on  $\mathbb{R}^d$ ,  $\mathcal{B}([0, T] \times \mathbb{R}^d$  is the Borel  $\sigma$ -field in  $[0, T] \times \mathbb{R}^d$ . Fix a constant  $K \in [0, \infty)$ .

Hypothesis (1)

(i) For any  $u \in W$  we have  $\sup_{(t,x)\in[0,T]\times\mathbb{R}^d} |u_t(x)| \leq K$ .

(ii) (Convexity of *W*.) If  $(\Omega, \mathcal{F}, P)$  is a probability space and  $u(\omega) = u_t(\omega, x)$  is an  $\mathcal{F} \times \mathcal{B}([0, T] \times \mathbb{R}^d)$ -measurable function such that  $u(\omega) \in W$  for any  $\omega$ , then the function  $E[u_t(x)]$  belongs to *W*.

(iii) ("Shift" invariance of W.) For  $u \in W$  and any bounded measurable  $\mathcal{G}$ -valued function  $g_t$  given on [0, T], the function  $u_t(g_t x)$  is in W.

#### Example

Fix a constant  $K_0 \in (0, \infty)$  and let *W* be the set of Borel functions on  $[0, T] \times \mathbb{R}$  satisfying, for each  $t \in [0, T]$ ,

$$0 \leq u_t(x) \leq 1$$
,  $\int_{\mathbb{R}} u_t^2(x) dx \leq K_0$ .

Then Hypothesis 1 is satisfied if  $\mathcal{G}$  is the group of translations of  $\mathbb{R}$ .

Next, let  $L := \{L_t, t \in (0, T)\}$ , be a family of linear operators

 $L_t: C_0^\infty(\mathbb{R}^d) \to B(\mathbb{R}^d)$ 

and take and fix

 $f \in B_c((0,T), C_0^{\infty}(\mathbb{R}^d)), \quad u_0 \in B(\mathbb{R}^d).$ 

#### Hypothesis (2)

The couple (L, f) is *W*-regular in the following sense.

(i) (9 and *L* commute.) For any  $t \in (0, T)$  and  $g \in \mathcal{G}$ , we have  $gL_t = L_t g$ . (ii) For  $\zeta \in C_0^{\infty}(\mathbb{R}^d)$ ,  $L_t \zeta(x) := (L_t \zeta)(x)$  is measurable with respect to (t, x) and

$$\int_{[0,T]\times\mathbb{R}^d} |L_t\zeta(x)| dt dx < \infty.$$

(iii) There is a mapping  $B((0, T), \mathfrak{G}) \to W$  sending  $h \in B((0, T), \mathfrak{G})$  into  $u[h] \in W$  such that u = u[h] has initial condition  $u_0$  and satisfies

$$\partial_t u_t(x) = L_t^* u_t(x) + (h_t f_t)(x), \quad t \in [0, T], \ x \in \mathbb{R}^d$$
(22)

(iv) For any  $h', h'' \in B((0, T), \mathfrak{G})$  and  $(t, x) \in [0, T] \times \mathbb{R}^d$ , we have

$$|u_t[h'](x) - u_t[h''](x)| \leqslant K \int_0^t \sup_{y \in \mathbb{R}^d} |f_r(h'_r y) - f_r(h''_r y)| \, dr.$$
(23)

 $u \in W$  satisfies (21) with initial condition  $u_0$  if, for any  $\zeta \in C_0^{\infty}(\mathbb{R}^d)$ ,  $t \in [0, T]$ ,

$$(u_t,\zeta):=\int_{\mathbb{R}^d}u_t(x)\zeta(x)dx=(u_0,\zeta)+\int_0^t(u_s,L_s\zeta)\,ds+\int_0^t(h_sf_s,\zeta)\,ds.$$

#### Theorem

Assume Hypotheses (1) and (2). For any  $g^{(1)}, ..., g^{(n)} \in B((0, T), \mathcal{G})$  and  $\lambda_1, ..., \lambda_n \ge 0$ , the couple, consisting of the family of operators  $\hat{L}_t$ , such that

$$\hat{L}_t^* = L_t^* + \sum_{i=1}^n \lambda_i (g_t^{(i)} - 1),$$
(24)

where 1 stands for the operation of multiplying by one, and f, is W-regular.

Now we add another assumption:

Hypothesis (3)

For any sequence  $u^k \in W$  and a bounded function  $u = u(t, x) = u_t(x)$ ,  $(t, x) \in [0, T] \times \mathbb{R}^d$ , such that

$$\int_{\mathbb{R}^d} u_t^k(x)\zeta(x)\,dx \to \int_{\mathbb{R}^d} u_t(x)\zeta(x)\,dx$$

for any  $t \in [0, T]$  and  $\zeta \in C_0^{\infty}(\mathbb{R}^d)$ , there exists  $w \in W$  such that  $w_t = u_t$  (a.e.) on  $\mathbb{R}^d$  for any  $t \in [0, T]$ .

Let  $\mathfrak{N}$  be a subset of the space of affine transformations of  $\mathbb{R}^d$  and suppose that

$$\mathcal{G} = \{ e^{t\nu} : t \in \mathbb{R}, \nu \in \mathfrak{N} \},\tag{25}$$

where by  $e^{t\nu}$  we mean a transformation g(t) defined as a unique solution of the equation

$$g(t) = 1 + \int_0^t v g(s) \, ds.$$
 (26)

We keep the assumption that *G* is a commutative group of volume-preserving transformations.

With any  $v \in \mathfrak{N}$  we associate an operator  $M_v$  acting on smooth functions  $\phi : \mathbb{R}^d \to \mathbb{R}$  by the formula

$$M_{\mathbf{v}}\phi(x) = \frac{d^2}{(d\varepsilon)^2} \phi(e^{\varepsilon \mathbf{v}}x)\big|_{\varepsilon=0} = (\mathbf{v}x)^i (\mathbf{v}x)^j D_{ij}\phi(x) + (\mathbf{v}^2 x - \mathbf{v}0)^i D_i\phi(x).$$

#### Example (1)

Let *l* be a unit vector in  $\mathbb{R}^d$  and define a transformation  $v = v_l$  by  $v_l x \equiv l$  on  $\mathbb{R}^d$ . Then (25) becomes

$$g(t)x = x + \int_0^t vg(s)x \, ds = x + \int_0^t l \, ds = x + tl.$$

Observe that in this example, for smooth  $\phi$ , we have  $M_{\nu}\phi(x) = D_l^2\phi(x)$ .

Thus, if  $\mathfrak{N} = \{\mathbf{v}_l : l \in \mathbb{R}^d, |l| = 1\}$ , then  $\mathfrak{G}$  is the set of shifts of  $\mathbb{R}^d$  and  $\mathfrak{G}$  is a commutative group.

#### Example (2)

Let vx = Qx, where Q is a skew-symmetric  $d \times d$ -matrix as in the previous example (see (20))

Then  $g_t x = e^{tv} x = (\exp[tQ])x$ , where  $\exp[tQ]$  is an orthogonal matrix. In this example, for smooth  $\phi$ ,

$$M_{\nu}\phi(x) = (Qx)^i (Qx)^j D_{ij}\phi(x) + (Q^2x)^i D_i\phi(x).$$

## A further result

Let W,  $\mathcal{G}$ , L,  $u_0$ , and f satisfy Hypotheses (1), (2) and (3). with  $\mathcal{G}$  from (24). Then, for any  $\mu^{(1)}$ , ...,  $\mu^{(n)} \in B((0, T), \mathfrak{N})$  equation (21) with

$$L_t^* + \sum_{i=1}^n M_{\mu_t^{(i)}}$$

in place of  $L_t^*$  and initial condition  $u_0$  has a solution in W.

C

To apply this result to Example (2) we fix the datum f and denote by  $A_0$  and  $A_{\alpha}$  the right-hand sides of (18) and (19), respectively. Then introduce

$$W = \{ u \in B([0,T] \times \mathbb{R}^2) : u_t \in C^{2+\alpha}(\mathbb{R}^d), \ t \in [0,T], \sup_{(t,x) \in [0,T] \times \mathbb{R}^2} |u_t(x)|$$

$$+ \sup_{t \in [0,T]} \left| \int_{\mathbb{R}^2} |u_t(x)| \, dx \leqslant A_0, \sup_{t \in [0,T]} [D_l^2 u_t]_{C^{\alpha}(\mathbb{R}^2)} \leqslant A_{\alpha} \, \forall l \in S_1 \right\},$$

and let  $\mathfrak{N} = \{tQ : t \in \mathbb{R}\}$ , where  $Q = (Q_{ij})$  is a 2 × 2-matrix,  $Q^{ii} = 0$ ,  $Q^{12} = 1$ ,  $Q^{21} = -1$ , i = 1, 2. Q is skew-symmetric and  $\mathfrak{G} = \{e^{tQ}; t \in \mathbb{R}\}$  is a **group of rotations** of  $\mathbb{R}^2$ .

# One can check the hypotheses for *W* and $\Re$ , $u_0 = 0$ and $\Delta$ in place of $L_t$ .

# A useful lemma

#### Lemma

Let  $u \in C^{2+\alpha}(\mathbb{R}^d)$  be such that, for any unit vector  $l \in \mathbb{R}^d$ , we have

 $\sup_{x\in\mathbb{R}^d} [D_l^2 u(x+l\,\cdot\,)]_{C^{\alpha}(\mathbb{R})} \leqslant 1.$ 

*Then there exists a constant*  $N'(\alpha)$  *such that for any* i, j = 1, ..., d *we have* 

 $M:=[D_{ij}u]_{C^{\alpha}(\mathbb{R}^d)}\leqslant N'(\alpha).$ 

A hyperbolic system taken from the Evans book on PDEs [Evans]

$$\partial_t u_t^r(x) + B_j^{rk} D_j u_t^k(x) = g_t^r(x)$$
(27)

r = 1, ..., m, in  $(0, T) \times \mathbb{R}^d$  with zero initial condition, where the  $m \times m$  constant matrices  $B_j := (B_j^{rk}), j = 1, ..., d$ , are such that for any  $\xi \in \mathbb{R}^d$ , the matrix  $\xi^j B_j$  has *m* real eigenvalues. Assume that  $g_t(x) = (g_t^r(x))$  is an  $\mathbb{R}^m$ -valued measurable functions such that

$$\int_0^T \|g_t\|_{H^s(\mathbb{R}^d;\mathbb{R}^m)}^2 dt = A < \infty,$$

where s > m + d/2 and  $H^s(\mathbb{R}^d; \mathbb{R}^m) = W_2^s(\mathbb{R}^d; \mathbb{R}^m)$  are the usual fractional Sobolev spaces of  $\mathbb{R}^m$ -valued functions.

By following the proof of Theorem 5 in §7.3.3 of [Evans] one arrives at the conclusion that (26) with zero initial condition has a unique solution in class W, which consists of measurable functions  $u = u_t(x)$  on  $[0, T] \times \mathbb{R}^d$ , such that  $u_t \in C^{0,1}(\mathbb{R}^d; \mathbb{R}^m)$  (here  $C^{0,1}(\mathbb{R}^d; \mathbb{R}^m)$  is the usual space of  $\mathbb{R}^m$ -valued Lipschitz functions on  $\mathbb{R}^d$ ) for any  $t \in [0, T]$  and

$$\|u\|_{L_{2}([0,T]\times\mathbb{R}^{d};\mathbb{R}^{m})} + \sup_{t\in[0,T]} \|u_{t}\|_{C^{0,1}(\mathbb{R}^{d};\mathbb{R}^{m})} \leqslant N'A,$$
(28)

where N' is a constant independent of g.

Now take a bounded measurable  $d \times d$ -matrix valued function  $a = a_t$  which is symmetric and nonnegative for any  $t \in [0, T]$ .

Define  $\sigma_t = a_t^{1/2}$ . One knows that  $\sigma_t$  is also measurable and if  $\sigma_t^{(i)}$  is the *i*th column of  $\sigma(t)$ , i = 1, ..., d, then for smooth  $\phi = \phi(x)$ 

$$a_t^{ij}D_{ij}\Phi = \sum_{i=1}^d D^2_{\sigma_t^{(i)}}\Phi$$

Therefore, by our last theorem, system (26) with the additional terms on the right-hand side  $a_t^{ij}D_{ij}u_t^r(x)$  has a solution of class *W*.

In particular, estimate (27) holds for the solution of the new system with the *same* right-hand side. The system seems to be of unknown type.

It is worth mentioning that the fact that estimate (27) holds for the new system with a constant N' independent of *a* can also be obtained by closely following the proof of Theorem 5 in §7.3.3 of [Evans].

*Still, what is important, we do not need to know how the initial result about (26) was obtained* 

#### A stochastic Poisson type process with values in $\mathcal{G}$

Take  $g \in B((0, T), \mathcal{G})$ , extend it to  $[0, \infty)$  by setting  $g_0 = 1$  and  $g_t = 1$  for  $t \ge T$ , where 1 is the operator of multiplying by 1.

Define  $h_t = h_t(\omega) \in \mathcal{G}$  for  $t \ge 0$  and  $\omega \in \Omega$  by

$$h_t = g_{\sigma_n} h_{\sigma_n} \quad \text{for} \quad t \in [\sigma_n, \sigma_{n+1}), \tag{29}$$
  
1, ..., where  $\sigma_0 - = 0 - := 0$  and  $h_0 x := x, x \in \mathbb{R}^d.$ 

In other terms,

n = 0.

$$h_t = \prod_{n \leqslant \pi_t} g_{\sigma_n} = \prod_{n \leqslant \pi_t} g_{\sigma_n \wedge t}.$$

Observe that the random variables  $\sigma_n \wedge t$  are  $\mathcal{F}_t$ -measurable.

Since  $g_t$  is measurable,  $g_{\sigma_n \wedge t}$  is  $\mathcal{F}_t$ -measurable. It follows that  $h_t$  is  $\mathcal{F}_t$ -measurable for each t, or, in other words, the process  $h_t$  is  $\mathcal{F}_t$ -adapted.

On the case  $\hat{L}_t^* = L_t^* + \lambda(g_t - 1)$ 

Let  $\zeta$  be a test function and  $\hat{h} \in B((0,T), \mathfrak{G})$ .

We prove that for each  $\omega$  and  $t \in [0, T]$  we have ( $h_t = h_t(\omega)$  as before)

$$(u_t[h\hat{h}], \zeta(h_t \cdot)) = (u_0, \zeta) + \int_0^t (u_s[h\hat{h}], L_s \zeta(h_s \cdot)) \, ds$$
$$+ \int_0^t (h_s \hat{h}_s f_s, \zeta(h_s \cdot)) \, ds$$
$$+ \int_{(0,t]} \left[ (u_s[h\hat{h}], \zeta(g_s h_{s-} \cdot)) - \xi_{s-} \right] d\pi_s$$

where

$$\xi_t = (u_t[h\hat{h}], \zeta(h_t \cdot)).$$

Then introduce

$$w_t(x) = E[u_t[h(\omega)\hat{h}](h_t^{-1}(\omega)x)]$$

We find

$$w_t(x) = u_0(x) + \int_0^t [L_r^* w_r(x) + \lambda (g_r^{-1} - 1) w_r(x) + \hat{h}_r f_r(x)] dr.$$