# The KPZ Equation and its space-time discretization 

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Durham Symposium, Stochastic Analysis

$$
\text { July 15, } 2017
$$

## The KPZ Equation and its Solution

The Kardar-Parisi-Zhang equation (KPZ) is formally given by

$$
\left(\partial_{t}-\Delta\right) h=\left(\partial_{x} h\right)^{2}+\xi \quad, \quad h(0, \cdot)=h_{0}(\cdot)
$$

where $h=h(t, x)$ is our stochastically growing height function, $h_{0}$ the initial condition and $\xi$ is space-time white noise.

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Set $u \xlongequal{\text { def }} \partial_{x} h$, then $u$ solves the Stochastic Burgers Equation (SBE)

$$
\left(\partial_{t}-\Delta\right) u=\partial_{x} u^{2}+\partial_{x} \xi \quad, \quad u(0, \cdot)=u_{0}(\cdot)
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## Space-Time Discretization

Let $\varepsilon>0, \Lambda_{\varepsilon^{2}, T} \xlongequal{\text { def }} \varepsilon^{2} \mathbb{Z} \cap(0, T]$ and $\mathbb{T}_{\varepsilon} \xlongequal{\text { def }} \varepsilon \mathbb{Z} \cap \mathbb{T}$. We want to consider

$$
\left(\bar{D}_{t, \varepsilon^{2}}-\Delta_{\varepsilon}\right) u^{\varepsilon}(z)=D_{x, \varepsilon} B_{\varepsilon}\left(u^{\varepsilon}, u^{\varepsilon}\right)(z)+D_{x, \varepsilon} \xi^{\varepsilon}(z), \quad u^{\varepsilon}(0, \cdot)=u_{0}^{\varepsilon}(\cdot)
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$$
B_{\varepsilon}(f, g)(x) \stackrel{\text { def }}{=} \int_{\mathbb{R}^{2}} f\left(x+\varepsilon y_{1}\right) g\left(x+\varepsilon y_{2}\right) \mu\left(\mathrm{d} y_{1}, \mathrm{~d} y_{2}\right),
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where $\mu$ is a symmetric measure supported on the integers.

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- $\mu=\frac{1}{3}\left(\delta_{(0,0)}+\frac{1}{2} \delta_{(0,1)}+\frac{1}{2} \delta_{(1,0)}+\delta_{(1,1)}\right)$, Zabusky/Sasamoto-Spohn


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AIM: Show that, in a suitable sense, $u^{\varepsilon} \longrightarrow u$ as $\varepsilon \rightarrow 0$.

## The Derivative of the KPZ Equation

Let $h$ be the solution to the KPZ equation, then formally $u \stackrel{\text { def }}{=} \partial_{x} h$ satisfies

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- Infer a suitable family of processes depending on $\xi$, that we will denote by $\mathbb{X}$


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Let $h$ be the solution to the KPZ equation, then formally $u \stackrel{\text { def }}{=} \partial_{x} h$ satisfies

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u_{\varepsilon}=P_{t} u_{0}+P^{\prime} *\left(u_{\varepsilon}^{2}\right)+P^{\prime} * \xi_{\varepsilon}
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on $[0, T] \times \mathbb{T}$, where $u_{0}$ is the initial condition, $\xi$ a space-time white noise,$\xi_{\varepsilon} \stackrel{\text { def }}{=} \xi * \varrho_{\varepsilon}$, $\varrho_{\varepsilon}$ a smooth mollifier, $P$ is the heat kernel, $P^{\prime} \xlongequal{\text { def }} \partial_{x} P$

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$$
v_{\varepsilon}=4 X_{\varepsilon}^{\dot{シ}}+2 P^{\prime} *\left(v_{\varepsilon} X_{\varepsilon}^{\bullet}\right)+P^{\prime} * F_{v_{\varepsilon}}^{\varepsilon}
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where $X_{\varepsilon}^{シ} \overbrace{}^{シ} \frac{1}{2}^{-}$and $X^{\bullet} \sim-\frac{1}{2}^{-}$．

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## IDEAS:

- Look for a solution with the following structure

$$
v(\bar{z})=v(z)+v^{\prime}(z)\left(X^{\prime}(\bar{z})-X^{\prime}(z)\right)+R(z, \bar{z})
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where $X^{\boldsymbol{*}}=P^{\prime} * X^{*}$ has regularity $\frac{1}{2}^{-}$and $R$ has regularity $>\frac{1}{2}$

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- Then, the product to be defined is $\tilde{R}^{*} \cdot(z, \bar{z}) \xlongequal{\text { def }}\left(X_{\varepsilon}^{*}(\bar{z})-X_{\varepsilon}^{*}(z)\right) X_{\varepsilon}^{*}(z)$.


## Making sense of the product and Fixed Point

- We want to make sense of the product $v_{\varepsilon} X_{\varepsilon}^{\bullet}$
- We made the ansatz $\delta_{z, \bar{z}} v=v^{\prime}(z) \delta_{z, \bar{z}} X^{\bullet}+\mathcal{C}^{\frac{1}{2}^{+}}$, where $X^{\boldsymbol{\varphi}}=P^{\prime} * X^{\bullet}$
- We need $\tilde{R}_{\varepsilon}^{\boldsymbol{\bullet}}(x, y) \stackrel{\text { def }}{=}\left(X_{\varepsilon}^{\boldsymbol{\varphi}}(y)-X_{\varepsilon}^{\boldsymbol{\bullet}}(x)\right) X_{\varepsilon}^{\bullet}(x)$


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1. The Stochastic term $\tilde{R}_{\varepsilon}^{\bullet}$ :

$$
\tilde{R}^{\bullet} \cdot \varepsilon(z, \bar{z})=\left(X_{\varepsilon}^{*}(\bar{z})-X_{\varepsilon}^{\dot{\varepsilon}}(z)\right) X_{\varepsilon}^{\dot{\varepsilon}}(z)
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$$
R^{\bullet \bullet} \cdot \varepsilon(z, \bar{z})=\left(X_{\varepsilon}^{\bullet}(\bar{z})-X_{\varepsilon}^{\bullet}(z)\right) X_{\varepsilon}^{\bullet}(z)-\mathbf{C}_{\varepsilon}
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2. The product $v_{\varepsilon} X_{\varepsilon}^{*}$ :

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\mathcal{R}_{t}(\mathbf{V} \bullet)_{t}(x)=V_{\varepsilon}(t, x) X_{\varepsilon}^{*}(t, x)
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## Theorem (Hairer '14, Gubinelli-Perkowski '15, C.-Matetski '16)

There exists a unique solution u to SBE. Moreover,

- the map $\mathcal{S}_{\text {SBE }}$ that assigns to $\left(u_{0}, \mathbb{X}\right) \in \mathcal{C}^{\eta} \times \mathcal{X}$ the solution $u$ is jointly locally Lipschitz continuous.


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- for a space-time white noise $\xi, \mathbb{X}\left(\xi_{\varepsilon}\right)$ converges to $\mathbb{X}(\xi)$ in $\mathcal{X}$, in probability.


## Sasamoto-Spohn type models

For $\varepsilon>0$, the family of discrete models we want to consider is

$$
\left(\bar{D}_{t, \varepsilon^{2}}-\Delta_{\varepsilon}\right) u^{\varepsilon}(z)=D_{x, \varepsilon} B_{\varepsilon}\left(u^{\varepsilon}, u^{\varepsilon}\right)(z)+D_{x, \varepsilon} \xi^{\varepsilon}(z), \quad u^{\varepsilon}(0, \cdot)=u_{0}^{\varepsilon}(\cdot)
$$

where
■ $z \in \Lambda_{\varepsilon^{2}, T} \times \mathbb{T}_{\varepsilon}$ for $\Lambda_{\varepsilon^{2}, T} \stackrel{\text { def }}{=}(0, T] \cap\left(\varepsilon^{2} \mathbb{Z}\right)$ and $\mathbb{T}_{\varepsilon} \xlongequal{\text { def }} \mathbb{T} \cap(\varepsilon \mathbb{Z})$

- $\left\{\xi^{\varepsilon}(z)\right\}_{z}$ is a family of i.i.d. centered normal random variables with variance $\varepsilon^{-3}$
- $B_{\varepsilon}$ is a bilinear map defined by

$$
B_{\varepsilon}(f, g)(x) \stackrel{\text { def }}{=} \int_{\mathbb{R}^{2}} f\left(x+\varepsilon y_{1}\right) g\left(x+\varepsilon y_{2}\right) \mu\left(\mathrm{d} y_{1}, \mathrm{~d} y_{2}\right),
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■ $\bar{D}_{t, \varepsilon^{2}}$ is the discrete forward difference and $D_{x, \varepsilon}, \Delta_{\varepsilon}$ are discrete operators

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## Expanding $u^{\varepsilon}$

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$$
v_{\varepsilon}=4 X^{\dot{\Downarrow}, \varepsilon}+2 D_{x, \varepsilon} P^{\varepsilon} *_{\varepsilon}\left(B_{\varepsilon}\left(V^{\varepsilon}, X^{\bullet}, \varepsilon\right)\right)+D_{x, \varepsilon} P^{\varepsilon} *_{\varepsilon} F_{v^{\varepsilon}}^{\varepsilon}
$$

where

$$
B_{\varepsilon}\left(V^{\varepsilon}, X^{\cdot,}\right)(x)=\int V^{\varepsilon}\left(x+\varepsilon y_{1}\right) X^{\cdot, \varepsilon}\left(x+\varepsilon y_{2}\right) \mu\left(\mathrm{d} y_{1}, \mathrm{~d} y_{2}\right)
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## IDEAS

- The discrete controlled structure we can expect is

$$
\delta_{z, \bar{z}} V^{\varepsilon}=V^{\prime, \varepsilon}(z) \int\left(X^{\phi_{,}, \varepsilon}\left(\bar{z}+\varepsilon y_{2}\right)-X^{\dagger, \varepsilon}\left(z+\varepsilon y_{2}\right)\right) \mu\left(\mathrm{d} y_{1}, \mathrm{~d} y_{2}\right)+R^{\varepsilon}(z, \bar{z})
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- The term to define is then

$$
\tilde{R}^{\bullet \cdot,}(x, y)=\int\left(X^{\bullet, \varepsilon}\left(y+\varepsilon y_{1}\right)-X^{\bullet, \varepsilon}\left(X+\varepsilon y_{1}\right)\right) X^{\bullet, \varepsilon}\left(y+\varepsilon y_{2}\right) \mu\left(\mathrm{d} y_{1}, \mathrm{~d} y_{2}\right)
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## Discrete Product and Renormalization

- the product is $B_{\varepsilon}\left(v^{\varepsilon}, X^{\bullet}, \varepsilon\right)(x)$

■ the ansatz $\delta_{z, \bar{z}} v^{\varepsilon}=v^{\prime}, \varepsilon(z) \int\left(X^{\boldsymbol{\varphi}}, \varepsilon\left(\bar{z}+\varepsilon y_{2}\right)-X^{\boldsymbol{\varphi}}, \varepsilon\left(z+\varepsilon y_{2}\right)\right) \mu\left(\mathrm{d} y_{1}, \mathrm{~d} y_{2}\right)+\ldots$

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1. The Stochastic term $\tilde{R}_{\varepsilon}^{*}$ :

$$
\tilde{R}^{\boldsymbol{\bullet}} \cdot \varepsilon(x, y)=\int\left(X^{\boldsymbol{\beta}, \varepsilon}\left(y+\varepsilon y_{1}\right)-X^{\bullet, \varepsilon}\left(X+\varepsilon y_{1}\right)\right) X^{\bullet, \varepsilon}\left(y+\varepsilon y_{2}\right) \mu\left(\mathrm{d} y_{1}, \mathrm{~d} y_{2}\right)
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2. The product $v_{\varepsilon} X_{\varepsilon}^{*}$ :

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\mathcal{R}_{t}^{\varepsilon}(\mathbf{V} \bullet)^{\varepsilon}(x)=B^{\varepsilon}\left(v^{\varepsilon}, X^{\bullet}, \varepsilon\right)(x)-\mathbf{C}^{\varepsilon} v^{\prime, \varepsilon}(t, x)
$$

where $B_{\varepsilon}\left(V^{\varepsilon}, X^{\bullet}, \varepsilon\right)(x)=\int V^{\varepsilon}\left(x+\varepsilon y_{1}\right) X^{\bullet}, \varepsilon\left(x+\varepsilon y_{2}\right) \mu\left(\mathrm{d} y_{1}, \mathrm{~d} y_{2}\right)$.

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## Convergence

## Theorem (C.-Matetski '16)

Let $\xi$ be a space-white noise and $\left\{\xi^{\varepsilon}(z)\right\} z$ be a family of independent rescaled normal random variable converging to $\xi$. Let $u^{\varepsilon}$ be the solution to

$$
\bar{D}_{t, \varepsilon^{2}} u^{\varepsilon}(z)=\Delta_{\varepsilon} u^{\varepsilon}(z)+D_{x, \varepsilon} B_{\varepsilon}\left(u^{\varepsilon}, u^{\varepsilon}\right)(z)-\mathbf{C} D_{x, \varepsilon} u^{\varepsilon}+D_{x, \varepsilon} \xi^{\varepsilon}(z), \quad u^{\varepsilon}(0, \cdot)=u_{0}^{\varepsilon}(\cdot)
$$

and $u$ be the solution to

$$
\partial_{t} u=\Delta u+\partial_{x} u^{2}-\mathbf{C} \partial_{x} u+\partial_{x} \xi, \quad u(0, \cdot)=u_{0}(\cdot)
$$

then if $u_{0}^{\varepsilon}$ converges to $u_{0}$ a.s. in $\mathcal{C}^{\eta}$, then $u^{\varepsilon}$ converges to $u$ in probability in $\mathcal{C}^{\alpha_{\star}-1}$.

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## Thank you for the attention!

