

# GL(2,R) geometry and integrable systems

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Plan:

- 1 Definitions
- 2 Motivations and examples
- 3  $GL(2, \mathbb{R})$ -structures and complex geometry
- 4 Dimension 4

# Definitions of $GL(2, \mathbb{R})$ -structures

Let  $M$  be a manifold of dimension  $k + 1$ .

Three equivalent definitions:

- 1 An isomorphism

$$TM \simeq S^k(E)$$

where  $E$  is a rank-2 bundle over  $M$ . Fixing a basis  $(x, y) \in E_p$

$$T_p M \simeq H_k(\mathbb{R}^2)$$

where  $H_k(\mathbb{R}^2)$  is the space of homogeneous polynomials in two variables and of order  $k$ .

- 2 A reduction of the frame bundle to a  $GL(2, \mathbb{R})$ -subbundle  $B(E)$  (where  $GL(2, \mathbb{R})$ -acts irreducibly).
- 3 A field of rational normal curves  $p \mapsto C(E)_p \subset P(T_p M)$

$$C(E) = \{(sx + ty)^k\}.$$

Why  $GL(2, \mathbb{R})$ -structures are interesting:

- 1 Natural geometric structures on solutions spaces of ODEs (generalisation of 3-dim conformal Lorentzian metric) [Bryant, Dunajski-Tod, Nurowski, Doubrov].
- 2 Can appear as characteristic varieties of PDEs, e.g. Veronese hierarchy on the next slide, or recent results by [Ferapontov-Kruglikov].

Solutions  $w : \mathbb{R}^{k+1} \rightarrow \mathbb{R}$  to

$$(a_i - a_j)\partial_0 w \partial_i \partial_j w + a_j \partial_i w \partial_j \partial_0 w - a_i \partial_j w \partial_i \partial_0 w = 0, \quad i, j = 1, \dots, k$$

where  $a_i$  are distinct numbers are in a one to one correspondence with

- 1 Hyper-CR Einstein-Weyl structures in dim 3 (i.e. for  $k = 2$ ) [Dunajski-K.].
- 2 Veronese webs on  $\mathbb{R}^{k+1}$  for arbitrary  $k$ . The Veronese webs are special 1-parameter families of corank-1 foliations introduced by Gelfand and Zakharevich in connection to bi-Poisson systems on odd-dimensional manifolds.

A characteristic variety of the system is the null cone  $C(E)$  of a  $GL(2, \mathbb{R})$ -structure.

Fix a point  $V$  in the null cone  $C(E)_p$ . Let

$$\text{span}\{V\} = D_1(V) \subset D_2(V) \subset \dots \subset D_k(V) \subset T_p M$$

be a sequence of osculating spaces of  $C(E)_p$  at  $V$ , where  $\dim D_i(V) = i$ .

Definitions:

- 1  $D_i(V)$  is called  $\alpha_i$ -plane of a  $GL(2, \mathbb{R})$ -structure.
- 2 A submanifold  $N \subset M$  is called  $\alpha_i$ -manifold if each  $T_p N$  is an  $\alpha_i$ -plane.
- 3 A structure is  $\alpha_i$ -integrable if all  $\alpha_i$ -planes are tangent to  $\alpha_i$ -manifolds.

- 1  $\alpha_i$ -integrability implies  $\alpha_j$ -integrability for  $j < i$ .
- 2  $\alpha_k$ -integrability is equivalent to  $\alpha_{k-1}$ -integrability (this follows from the geometry of Goursat flags).
- 3 Veronese webs are  $\alpha_i$ -integrable for any  $i$ .



## Theorem

*A  $GL(2, \mathbb{R})$ -structure in dimension  $k + 1$  comes from an ODE of order  $k + 1$  with the vanishing Wünschmann invariants if and only if it is  $\alpha_k$ -integrable.*

## Remarks:

- 1 The Wünschmann invariants are the basic contact invariants of ODEs. An ODE of order  $k + 1$  has  $k - 1$  Wünschmann invariants.
- 2 If one wants to make  $\alpha_k$ -manifolds totally geodesic w.r.t. some connection then additional point invariants appear - this generalizes the Cartan invariant for third-order ODEs and the corresponding Einstein-Weyl structures.

We shall consider later the  $\alpha_{\frac{k+1}{2}}$ -integrability for even-dimensional manifolds.

## Theorem (K.-Mettler)

Let  $TM \simeq S^k(E)$  be a  $GL(2, \mathbb{R})$ -structure on even-dimensional manifold  $M$  and assume that a  $GL(2, \mathbb{R})$ -connection on  $B(E)$  is defined by a 1-form  $\phi = (\phi_j^i)_{i,j=1,2}$  with values in  $gl(2, \mathbb{R})$ . Then there is a canonical almost-complex structure  $J_\phi$  on the quotient bundle

$$B(E)/CO(2, \mathbb{R})$$

whose  $(1, 0)$ -forms pullback to  $B(E)$  to become linear combinations of the forms  $\xi^{k,0}, \dots, \xi^{k, \lfloor \frac{k}{2} \rfloor}$  and

$$\zeta = (\phi_2^1 + \phi_1^2) + i(\phi_2^2 - \phi_1^1),$$

where  $\xi^{k,0}, \dots, \xi^{k, \lfloor \frac{k}{2} \rfloor}$  are certain complex valued forms composed from the soldering form.

In dimension 4:

$$\xi^{3,1} = \frac{1}{4}(3\omega^0 + \omega^2 + i(\omega^1 + 3\omega^3)), \quad \xi^{3,0} = \frac{1}{4}(\omega^0 - \omega^2 + i(\omega^1 - \omega^3)).$$

In dimension 6:

$$\xi^{5,2} = \frac{1}{76}(10\omega^0 + 7\omega^3 + 12\omega^5 + i(12\omega^2 + 7\omega^4 + 10\omega^6)),$$

$$\xi^{5,1} = \frac{1}{76}(5\omega^0 - 6\omega^3 - 13\omega^5 + i(13\omega^2 + 6\omega^4 - 5\omega^6)),$$

$$\xi^{5,0} = \frac{1}{76}(\omega^0 - 5\omega^3 + 5\omega^5 + i(5\omega^2 - 5\omega^4 + \omega^6)).$$

# Complex structure on $H_k(\mathbb{R}^2)$

The first step in the proof is a construction of a complex structure on the space of polynomials.  $H_k(\mathbb{R}^2)$  decomposes into 2-dimensional subspaces, invariant w.r.t.  $CO(2, \mathbb{R})$ . The polynomials are

$$H_{k-2i} = \text{span}\{\Re((x + iy)^{k-i}(x - iy)^i), \Im((x + iy)^{k-i}(x - iy)^i)\}.$$

On  $H_j$  we defined a complex structure by formula

$$J_j = \sqrt[j]{J}$$

where  $J \in CO(2, \mathbb{R})$  is the standard complex structure  $(x, y) \mapsto (-y, x)$ .

The construction gives  $(x + iy)^{k-i}(x - iy)^i$  as  $(1, 0)$ -vectors.

The torsion  $T$  and curvature  $C$  of  $\phi$  in the presence of  $J_\phi$  decompose to parts  $T^{(2,0)}$ ,  $T^{(1,1)}$ ,  $T^{(0,2)}$  and  $C^{(2,0)}$ ,  $C^{(1,1)}$ ,  $C^{(0,2)}$ .

## Theorem (K.-Mettler)

*The almost-complex structure  $J_\phi$  on  $B(E)/CO(2, \mathbb{R})$  is integrable if and only if  $T^{(0,2)} = 0$  and  $C^{(0,2)} = 0$ .*

Remark: If  $T^{(1,1)} = 0$  and  $T^{(0,2)} = 0$  then  $C^{(0,2)} = 0$ . In particular, if  $\phi$  is torsion-free then  $J_\phi$  is integrable.

# Canonical connection

One can define a canonical connection for a  $GL(2, \mathbb{R})$ -structure. The corresponding almost-complex structure will be called canonical.

Let  $\mathfrak{g}_k \subset \mathfrak{gl}(k+1, \mathbb{R})$  be the standard subalgebra isomorphic to  $\mathfrak{gl}(2, \mathbb{R})$  corresponding to the irreducible action on  $H_k(\mathbb{R}^2)$ . Define

$$\mathfrak{g}_k^\perp = \{\psi \in \mathfrak{gl}(k+1, \mathbb{R}) \mid \text{tr}(\eta \circ \psi) = 0 \quad \forall \eta \in \mathfrak{g}_k\}.$$

## Theorem

*Let  $TM \simeq S^k(E)$  be a  $GL(2, \mathbb{R})$ -structure on a manifold  $M$  of dimension  $k+1 > 3$ . There is a unique  $GL(2, \mathbb{R})$ -connection  $\phi = (\phi_j^i)_{i,j=1,2}$  with values in  $\mathfrak{gl}(2, \mathbb{R})$  such that  $\Theta_\chi(X, \cdot) \in \mathfrak{g}_k^\perp$  for any  $\chi \in B(E)$  and  $X \in T_\chi B(E)$ , where  $\Theta$  is the torsion 2-form of  $\psi$ .*

Remark: In dimension 4 this coincides with the Bryant connection.

## Theorem

Let  $TM \simeq S^k(E)$  be a  $GL(2, \mathbb{R})$ -structure on even-dimensional manifold  $M$  and assume that the almost-complex structure  $J_\phi$  defined by a  $GL(2, \mathbb{R})$ -connection  $\phi$  is integrable. Then, the  $GL(2, \mathbb{R})$ -structure is  $\alpha_{\frac{k+1}{2}}$ -integrable.

## Remarks:

- 1 In dimension 4 we get that a  $GL(2, \mathbb{R})$ -structure is torsion-free if and only if the canonical almost-complex structure is integrable.
- 2 If a structure is  $\alpha_{\frac{k+1}{2}}$ -integrable then there is a well defined  $\frac{k+3}{2}$ -dimensional (real) twistor space. (This twistor space can be "glued" to  $B(E)/C(2, \mathbb{R})$  to get (complex) twistor space.)

$B(E)/CO(2, \mathbb{R}) \simeq P(E^{\mathbb{C}}) \setminus P(E)$  and any point

$$[z] = [x + iy] \in P(E^{\mathbb{C}}) \setminus P(E)$$

defines the following subspace in  $T^{\mathbb{C}}M \simeq S^k(E^{\mathbb{C}})$

$$\text{span}\{z^k, z^{k-1}\bar{z}, \dots, z^{\frac{k+1}{2}}\bar{z}^{\frac{k-1}{2}}\}$$

This defines a complex structure on  $T_pM$ .

Remark: Holomorphic sections of  $B(E)/CO(2, \mathbb{R})$  give complex structures on  $M$ .



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Now, we would like to describe all integrable  $GL(2, \mathbb{R})$ -structures in a convenient way.

## Theorem (K.-Mettler)

Any integrable  $GL(2, \mathbb{R})$ -structure in dim 4 can be put in the form  $C(E) = \{ s^3 V_0 + s^2 t V_1 + s t^2 V_2 + t^3 V_3 \mid s, t \in \mathbb{R} \}$  where

$$\begin{aligned} V_0 &= \partial_3, & V_1 &= \partial_2 + 9A\partial_3, & V_2 &= \partial_1 + 3A\partial_2 + B\partial_3, \\ V_3 &= \partial_0 + A\partial_1 + C\partial_2 + D\partial_3, \end{aligned}$$

and  $A, B, C, D$  are functions satisfying the following system

$$\begin{aligned} V_2(D) - V_3(B) - BV_2(A) - 9AV_2(C) + 27AV_3(A) + 27A^2V_2(A) &= 0 \\ 3V_2(C) + 9V_3(A) - 2V_1(D) - 9AV_2(A) + 2BV_1(A) \\ &\quad + 18AV_1(C) - 54A^2V_1(A) = 0 \\ 3V_2(A) - 6V_1(C) + 3V_0(D) + 18AV_1(A) - 27AV_0(C) \\ &\quad + 81A^2V_0(A) - 3BV_0(A) = 0 \\ 3V_1(A) + 9V_0(C) - 2V_0(B) + 27AV_0(A) &= 0 \end{aligned}$$

## Remarks:

- 1 First step in the proof: write down a structure in terms of the corresponding ODE.
- 2 A priori there are 8 equations (components of the Bryant torsion) however half of them is void.
- 3 The system has a Lax representation  $[L_0, L_1] = 0$ .
- 4 I do not know how to construct a similar system describing the structures in higher dimensions.

Thank you!