

# Cloaking and superlensing using negative index materials

Durham Symposium on Mathematical and Computational Aspects of Maxwell's  
Equations

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# Outline

- 1 Negative index materials
- 2 Two interesting examples.
- 3 Superlensing using complementary media
- 4 Cloaking using complementary media
- 5 Summary

# Part 1: Negative index materials

## Negative index materials (NIMs)

**Definition:** NIMs are artificial structures where the refractive index has a negative value over some frequency range.

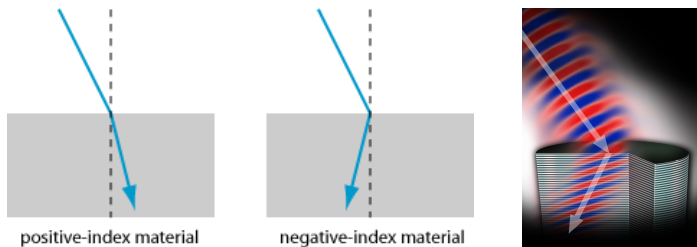


Figure: Left: RP-photonics; Right: Wikipedia.

### Highlights of the development

- 1 Veselago (UFN 64) investigated theoretically NIMs.
- 2 Nicorovici, McPhedran, & Milton (PRB 94) and Pendry (PRL 00).
- 3 Shelby et al. (Science 01) confirmed experimentally.

## Mathematical settings

Electromagnetic setting:

$$\begin{cases} \nabla \times \mathbf{E} = i\mathbf{k}\mu\mathbf{H}, \\ \nabla \times \mathbf{H} = -i\mathbf{k}\epsilon\mathbf{E} + \mathbf{j}. \end{cases}$$

Negative index materials:  $\epsilon < 0$  and  $\mu < 0$ .

Acoustic setting:

$$\operatorname{div}(\Lambda \nabla u) + k^2 \Sigma u = f.$$

Negative index materials:  $\Lambda < 0$  and  $\Sigma < 0$ .

Remarks:

- 1 The ellipticity and compactness might be lost.
- 2 Localized resonance might appear.
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## Part 2: Two examples



# First example: Nicorovici, McPhedran, & Milton's result, PRB 94

Consider

$$\operatorname{div}(A_\delta \nabla u_\delta) = f \text{ in } \mathbb{R}^2 \text{ where}$$

$$A_\delta = \begin{cases} 1 & \text{in } \mathbb{R}^2 \setminus B_{r_2}, \\ -1 - i\delta & \text{in } B_{r_2} \setminus B_{r_1}, \\ 1 & \text{in } B_{r_1}. \end{cases}$$

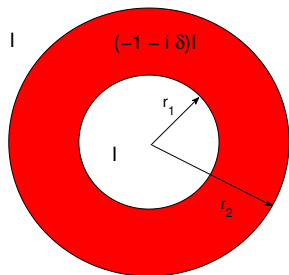
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If  $\operatorname{supp} f \cap B_{r_3} = \emptyset$  where  $r_3 = r_2^2/r_1$ , then

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## Some questions:

- Why do the phenomena hold for  $r_3 = r_2^2/r_1$ ?
- Is it necessary that the geometry is radial symmetric?
- What happens in the finite frequency case ( $k \neq 0$ ) and in three dimensions?



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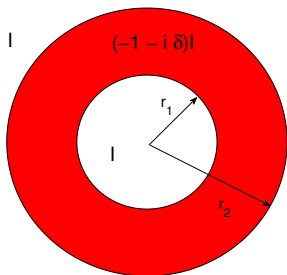
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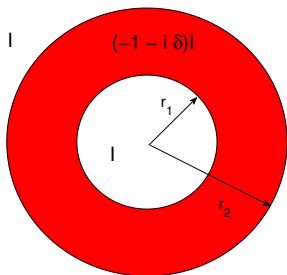
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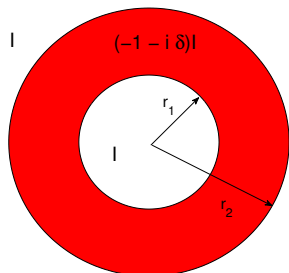
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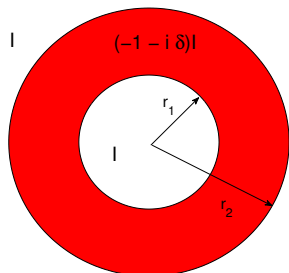
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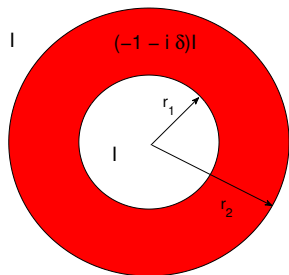
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## Part 3: Superlensing using complementary media

## Superlensing using complementary media - State of the art

- **Veselago's lens** (slab lens): Veselago UFN 64 (ray theory), Pendry PRL 00 (Maxwell's equations).

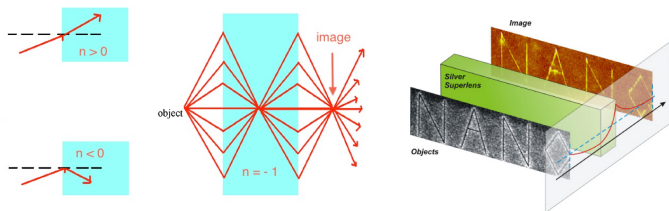
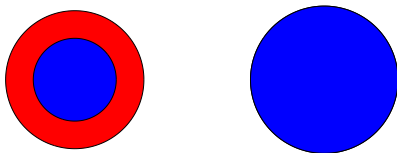


Figure: Left: Veselago's lens. Right: Yang et al.'s experiment Nature 08.

- **Cylindrical lens**: Nicorovici, McPhedran, Milton PRB 94 (quasistatic regime), Pendry OE 03 (finite frequency regime).
- **Spherical lens**: Ramakrishna & Pendry PRE 04 (finite frequency regime).

## State of the art contd.

- **Standard proposal:**
  - Cylindrical lens: To magnify  $m$  times “an object” in  $B_{r_0}$ , one puts a plasmonic structure  $-I$  in  $B_{r_2} \setminus B_{r_0}$  with  $r_2^2/r_0^2 = m$ .
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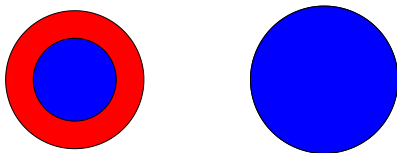


- **Known results** : “Object”: a constant isotropic object, homogeneous medium via separation of variables.
- **Comments**: The structure in 3d is **not easy** to predict. This was done by searching in the set of radial isotropic structures.
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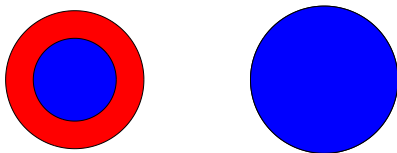
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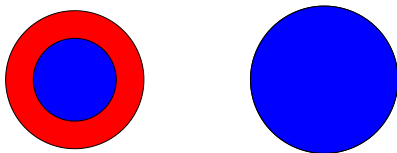
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## The two dimensional quasistatic regime, Ng, AIHP 15

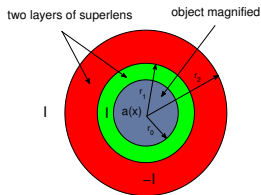
Magnified region:  $B_{r_0}$ ; Magnification:  $m > 1$ .

The superlensing device contains two layers:

- 1 The first one  $-I$  in  $B_{r_2} \setminus B_{r_1}$
- 2 The second (new) one  $I$  in  $B_{r_1} \setminus B_{r_0}$ .

Here  $r_2 = mr_0$  and  $r_1 = m^{1/2}r_0$ . With loss, the medium is

$$s_\delta A = \begin{cases} 1 \cdot I & \text{in } \Omega \setminus B_{r_2}, \\ (-1 - i\delta) \cdot I & \text{in } B_{r_2} \setminus B_{r_1}, \\ 1 \cdot I & \text{in } B_{r_1} \setminus B_{r_0}, \\ 1 \cdot a & \text{in } B_{r_0}. \end{cases}$$

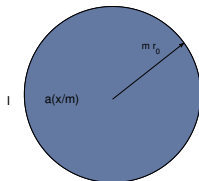


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## The two dimensional quasistatic regime, Ng, AIHP 15

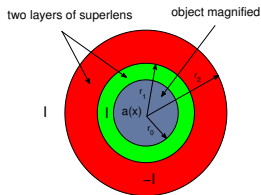
Magnified region:  $B_{r_0}$ ; Magnification:  $m > 1$ .

The superlensing device contains two layers:

- 1 The first one  $-I$  in  $B_{r_2} \setminus B_{r_1}$
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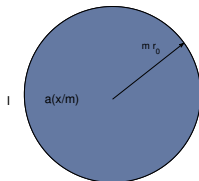


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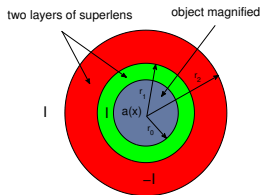
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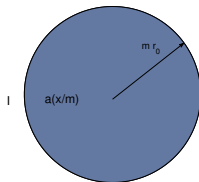


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## Proof.

We first consider the case  $\mathbf{a} = \mathbf{I}$  in  $B_{r_0}$ . Define

$$u_1(x^*) = u(x), \quad x^* = F(x) = r_2^2 x / |x|^2.$$

We have  $\partial B_{r_3} = F(\partial B_{r_1})$  and

$$\operatorname{div}(M \nabla u_1) = 0 \text{ in } \mathbb{R}^2 \setminus B_{r_2} \text{ where}$$

$$M = 1 \text{ in } B_{r_3} \setminus B_{r_2}, -1 \text{ in } \mathbb{R}^2 \setminus B_{r_3}.$$

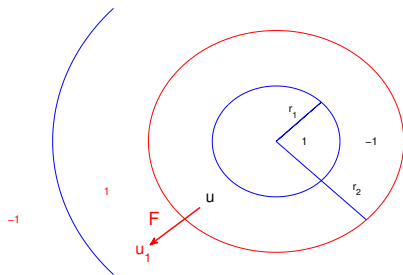
Thus

$$\Delta u_1 = \Delta u = 0 \text{ in } B_{r_3} \setminus B_{r_2}$$

$$u_1 - u = \partial_r u_1 - \partial_r u \Big|_{+} = 0 \text{ on } \partial B_{r_2}.$$

By the unique continuation principle,

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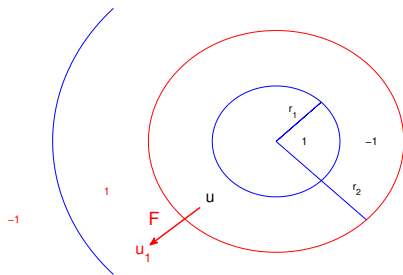
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## Proof.

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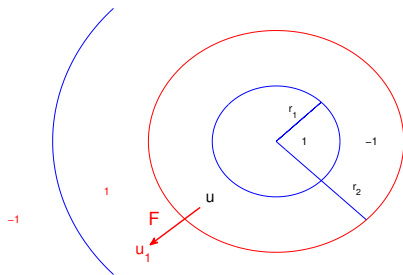
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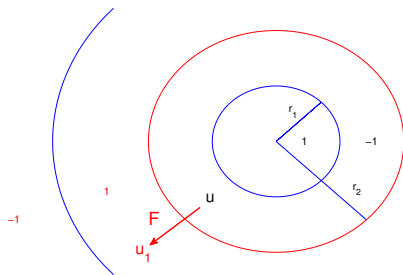
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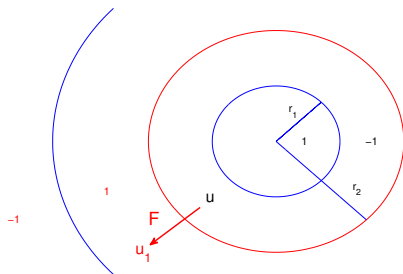
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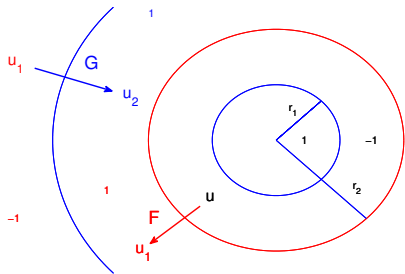
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$$\text{Set } \hat{\mathbf{u}} = \begin{cases} \mathbf{u} & \text{in } \Omega \setminus \bar{B}_{r_3} \\ \mathbf{u}_2 & \text{in } B_{r_3}. \end{cases}, \text{ then } \Delta \hat{\mathbf{u}} = \mathbf{f} \text{ in } \Omega.$$

The general case:  $\operatorname{div}(\hat{\Lambda} \nabla \mathbf{u}_2) = 0$  in  $B_{r_3}$  and  $\hat{\Lambda} = \mathbf{I}$  in  $B_{r_3} \setminus B_{r_1}$ . Therefore  $\mathbf{u}_2 = \mathbf{u}_1$  in  $B_{r_2} \setminus B_{r_1}$  and the conclusion follows.

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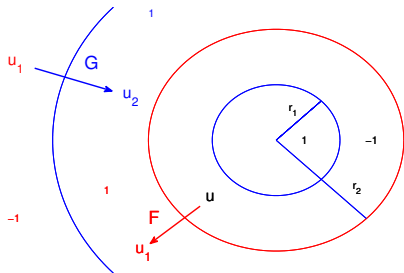
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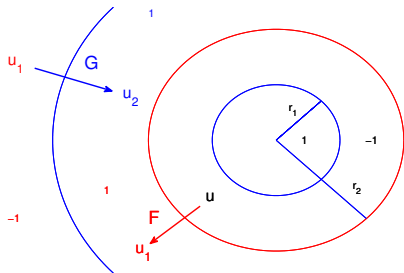
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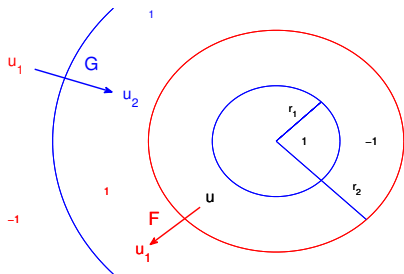
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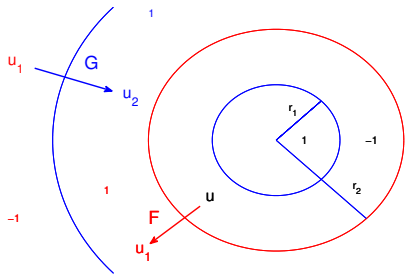
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### Lemma

Let  $d = 2, 3$ ,  $g \in H^{-1}(\Omega)$ ,  $A$  be uniformly elliptic in  $\Omega$ .  $\exists! v_\delta \in H_0^1(\Omega)$  to

$$\operatorname{div}(s_\delta A \nabla v_\delta) = g \text{ in } \Omega.$$

Moreover,

$$\|v_\delta\|_{H^1(\Omega)} \leq C \max\{1, 1/\delta\} \|g\|_{H^{-1}(\Omega)}.$$

Set  $v_\delta = u_\delta - u_0$ . Then

$$\operatorname{div}(s_\delta A \nabla v_\delta) = \operatorname{div}(s_\delta A \nabla u_\delta) - \operatorname{div}(s_\delta A \nabla u_0) = \operatorname{div}[(s_0 - s_\delta) A \nabla u_0].$$

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# What happens in the general case?

## Transformations optics

### Lemma

Let  $\Omega_1 \subset\subset \Omega_2 \subset\subset \Omega_3$  and  $T : \Omega_2 \setminus \Omega_1 \rightarrow \Omega_3 \setminus \Omega_2$ . Fix  $u$  defined in  $\Omega_2 \setminus \Omega_1$  and set  $v = u \circ T^{-1}$ . We have

$$\operatorname{div}(\alpha \nabla u) + \sigma u = f \text{ in } \Omega_2 \setminus \Omega_1 \text{ iff } \operatorname{div}(T_* \alpha \nabla v) + T_* \sigma v = T_* f \text{ in } \Omega_3 \setminus \Omega_2.$$

If  $T(x) = x$  on  $\partial\Omega_2$  then

$$v = u, \quad T_* \alpha \nabla v \cdot \eta_1 = -\alpha \nabla u \cdot \eta_1 \text{ on } \partial\Omega_2.$$

$$T_* \mathcal{A}(y) = \frac{DT(x)\mathcal{A}(x)DT^T(x)}{J(x)}, \quad T_* \Sigma(y) = \frac{\Sigma(x)}{J(x)}, \quad \text{and} \quad T_* f(y) = \frac{f(x)}{J(x)},$$

where  $x = T^{-1}(y)$  and  $J(x) = |\det DT(x)|$ .

Reflecting complementary media :  $T_* \alpha = \alpha$  and  $T_* \sigma = \sigma$  (Ng, TRANS 15).

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## Transformations optics

### Lemma

Let  $\Omega_1 \subset\subset \Omega_2 \subset\subset \Omega_3$  and  $T : \Omega_2 \setminus \Omega_1 \rightarrow \Omega_3 \setminus \Omega_2$ . Fix  $u$  defined in  $\Omega_2 \setminus \Omega_1$  and set  $v = u \circ T^{-1}$ . We have

$$\operatorname{div}(a \nabla u) + \sigma u = f \text{ in } \Omega_2 \setminus \Omega_1 \text{ iff } \operatorname{div}(T_* a \nabla v) + T_* \sigma v = T_* f \text{ in } \Omega_3 \setminus \Omega_2.$$

If  $T(x) = x$  on  $\partial\Omega_2$  then

$$v = u, \quad T_* a \nabla v \cdot \eta_1 = -a \nabla u \cdot \eta_1 \text{ on } \partial\Omega_2.$$

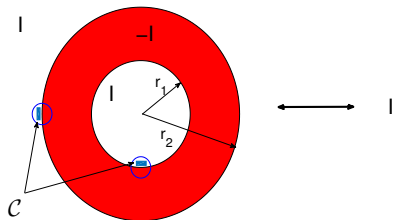
$$T_* \mathcal{A}(y) = \frac{DT(x) \mathcal{A}(x) DT^T(x)}{J(x)}, \quad T_* \Sigma(y) = \frac{\Sigma(x)}{J(x)}, \quad \text{and} \quad T_* f(y) = \frac{f(x)}{J(x)},$$

where  $x = T^{-1}(y)$  and  $J(x) = |\det DT(x)|$ .

**Reflecting complementary media** :  $T_* a = a$  and  $T_* \sigma = \sigma$  (Ng. TRANS 15).

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- 1 **Similar facts** hold for the Maxwell equations : Ng. 15.
- 2 The green layer can be **thinner** (Ng. AIHP 15) but **necessary** (Ng. 16).



Theorem (Ng. 16)

Let  $d = 2$  and  $f \in L^2(\Omega)$  be s.t.  $\text{supp } f \cap B_{r_3} = \emptyset$  where  $r_3 = r_2^2/r_1$ . We have

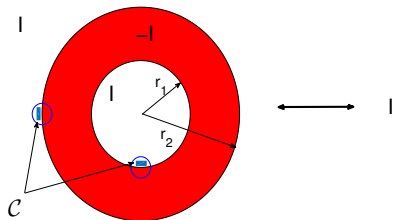
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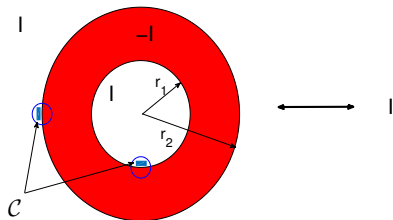
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## Part 4: Cloaking using complementary media

# Cloaking using complementary media

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Difficulty: Localized resonance + loss of ellipticity.

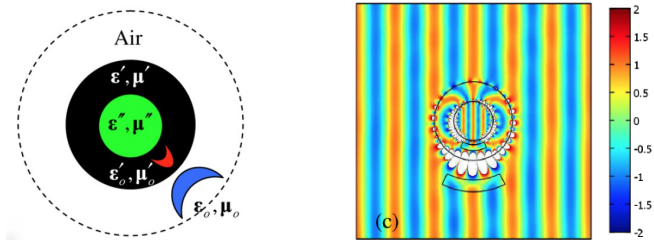


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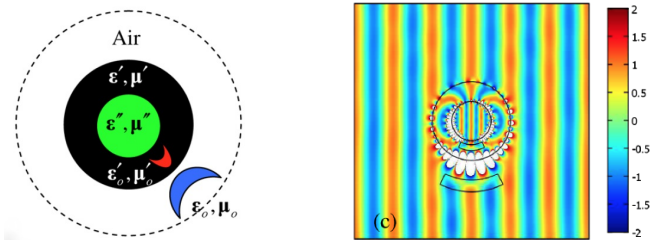


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## Our proposal

Our construction: 2 parts

- The first one is to **cancel** the effect of the cloaked region.
- The second part is to **fill** the space which "disappears" from the cancellation.
- For the first part, we slightly change the strategy of Lai et. al.'s. We consider  $B_{r_3} \setminus B_{r_2}$  as the cloaked region in which the medium is characterised by

$$b = \begin{cases} a & \text{in } B_{2r_2} \setminus B_{r_2}, \\ I & \text{in } B_{r_3} \setminus B_{2r_2}. \end{cases}$$

- The complementary media in  $B_{r_2} \setminus B_{r_1}$  is given by

$$-(F^{-1})_* b,$$

Here  $F: B_{r_2} \setminus \bar{B}_{r_1} \rightarrow B_{r_3} \setminus \bar{B}_{r_2}$  is the Kelvin's transform w.r.t.  $\partial B_{r_2}$ , i.e.,  $F(x) = r_2^2 x / |x|^2$ .

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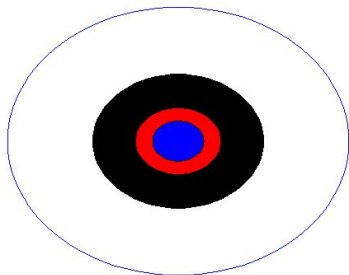
## Mathematics setting

To study the problem correctly, one needs to add some loss to the medium.  
With the loss, the medium is characterized by  $s_\delta A$ , where

$$A = \begin{cases} b & \text{in } B_{r_3} \setminus B_{r_2}, \\ F_*^{-1} b & \text{in } B_{r_2} \setminus B_{r_1}, \\ \left(r_3^2/r_2^2\right)^{d-2} I & \text{in } B_{r_1}, \\ I & \text{otherwise,} \end{cases}$$

and

$$s_\delta = \begin{cases} -1 + i\delta & \text{in } B_{r_2} \setminus B_{r_1}, \\ 1 & \text{otherwise.} \end{cases}$$





## Statement of the result

Let  $\Omega$  be a smooth open subset of  $\mathbb{R}^d$  ( $d = 2, 3$ ) such that  $B_{r_3} \subset\subset \Omega$ . Given  $f \in L^2(\Omega)$ , let  $u_\delta, u \in H_0^1(\Omega)$  be resp. the unique solution to

$$\operatorname{div}(s_\delta A \nabla u_\delta) = f \text{ in } \Omega, \quad (0.1)$$

and

$$\Delta u = f \text{ in } \Omega. \quad (0.2)$$

### Theorem (Ng.)

Let  $d = 2, 3$ ,  $f \in L^2(\Omega)$  with  $\operatorname{supp} f \subset \Omega \setminus B_{r_3}$ . There exists  $m > 0$  s.t. if  $r_3 > mr_2$  then

$$u_\delta \rightarrow u \text{ weakly in } H^1(\Omega \setminus B_{r_3}) \text{ as } \delta \rightarrow 0.$$

For an observer outside  $B_{r_3}$ , the medium in  $B_{r_3}$  looks like I: one has cloaking.

## Sketch of the proof

We have

$$\|\mathbf{u}_\delta\|_{H^1(\Omega)} \leq C\delta^{-1/2}\|f\|_{L^2(\Omega)}^{1/2}\|\mathbf{u}_\delta\|_{L^2(\Omega \setminus B_{r_3})}^{1/2} (\sim \delta^{-1/2}) \quad (0.3)$$

Let  $\mathbf{u}_{1,\delta}$  be the refl. of  $\mathbf{u}_\delta$  through  $\partial B_{r_2}$  and  $\mathbf{u}_{2,\delta}$  be the refl. of  $\mathbf{u}_{1,\delta}$  through  $\partial B_{r_3}$  (by F and G, the Kelvin's transform w.r.t.  $\partial B_{r_2}$  and  $\partial B_{r_3}$ ). We have

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$\widetilde{W}_\delta \rightarrow \mathbf{u}$ . The proof would be complete. **This is not true in general !!!**

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Recall

$$\operatorname{div}(b\nabla u_{1,\delta}) = 0 \text{ in } B_{r_3} \setminus B_{r_2} \quad \text{and} \quad \Delta u_{2,\delta} = 0 \text{ in } B_{r_3}.$$

Three spheres inequality, if  $\operatorname{div}(A\nabla V) = 0$  in  $B_{r_3}$ , then

$$\|V\|_{L^2(\partial B_{2r_2})} \leq C \|V\|_{L^2(\partial B_{r_2})}^\alpha \|V\|_{L^2(\partial B_{r_3})}^{1-\alpha}.$$

Since  $u_\delta = u_{1,\delta}$  and  $\partial_r u_\delta = (1 - i\delta)\partial_r u_{1,\delta}$  on  $\partial B_{r_2}$ , it follows that if  $r_3 \gg r_2$ ,

$$u_\delta - u_{1,\delta} \text{ is small on } \partial B_{2r_2}.$$

Define

$$W_\delta = \begin{cases} u_\delta & \text{in } \Omega \setminus B_{r_3}, \\ u_{2,\delta} - (u_{1,\delta} - u_\delta) & \text{in } B_{r_3} \setminus B_{2r_2}, \\ u_{2,\delta} & \text{in } B_{2r_2}. \end{cases}$$

Then  $\Delta W_\delta = f$  in  $\Omega \setminus (\partial B_{r_3} \cup \partial B_{2r_2})$ ,  $[W_\delta]$  and  $[A\nabla W_\delta \cdot \nu]$  are **small** on  $\partial B_{r_3} \cup \partial B_{2r_2}$  and  $W_\delta = u_\delta$  in  $\Omega \setminus B_{r_3}$ . The conclusion follows.  $\square$

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- Two interesting examples.
- Superlensing using complementary media
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