

# Difference Equations on Graphs

Józef Dodziuk

Queens College and the Graduate Center  
of The City University of New York

LMS Symposium on Graph Theory

July, 2013

# First LMS Durham Symposium Schedule

ON GLOBAL RIEMANNIAN GEOMETRY

11th - 22nd July 1974

## PROGRAMME

### Tuesday 16th

- |               |                            |   |
|---------------|----------------------------|---|
| 9.30 - 10.45  | Dr. W. Schmid              | "Moduli of Algebraic manifolds"<br>(continued)                            |
| 11.15 - 12.30 | Professor M.F. Atiyah      | "Eigenvalues of the Laplacian -<br>Introduction and Historical<br>Survey" |
| 5.00 - 6.15   | Professor H. Duistermaat I | "Eigenvalues and Closed<br>Geodesics"                                     |

### Thursday 18th

- |               |                             |                             |
|---------------|-----------------------------|-----------------------------|
| 9.30 - 10.45  | Professor H. Duistermaat II | "Clustering of Eigenvalues" |
| 11.15 - 12.30 | Professor I.M. Singer       | "Reidemeister Torsion"      |
| 5.00 - 6.15   | Mr. J. Dodziuk              | "Combinatorial Laplacians"  |

## Laplacian in Graph and Riemannian Settings

In Riemannian Geometry the Laplacian on functions is defined as

$$\Delta u = -\frac{1}{\sqrt{g}} \sum \frac{\partial}{\partial x^i} \left( \sqrt{g} g^{ij} \frac{\partial u}{\partial x^j} \right) = -g^{ij} \frac{\partial^2 u}{\partial x^i \partial x^j} + \dots$$

where  $g_{ij}$  are components of the metric tensor,  $g = \det(g_{ij})$ , and  $(g^{ij}) = (g_{ij})^{-1}$ . Thus the Laplace operator contains in it **the complete information** about the geometry.

## Laplacian in Graph and Riemannian Settings

In Riemannian Geometry the Laplacian on functions is defined as

$$\Delta u = -\frac{1}{\sqrt{g}} \sum \frac{\partial}{\partial x^i} \left( \sqrt{g} g^{ij} \frac{\partial u}{\partial x^j} \right) = -g^{ij} \frac{\partial^2 u}{\partial x^i \partial x^j} + \dots$$

where  $g_{ij}$  are components of the metric tensor,  $g = \det(g_{ij})$ , and  $(g^{ij}) = (g_{ij})^{-1}$ . Thus the Laplace operator contains in it **the complete information** about the geometry.

For a graph  $K = (V, E)$  (without loops and double connections) and a real-valued function  $u$  on the set  $V$  of vertices, the combinatorial Laplacian is given by

$$Lu(x) = \sum_{y \sim x} (u(x) - u(y))$$

## Laplacian in Graph and Riemannian Settings

In Riemannian Geometry the Laplacian on functions is defined as

$$\Delta u = -\frac{1}{\sqrt{g}} \sum \frac{\partial}{\partial x^i} \left( \sqrt{g} g^{ij} \frac{\partial u}{\partial x^j} \right) = -g^{ij} \frac{\partial^2 u}{\partial x^i \partial x^j} + \dots$$

where  $g_{ij}$  are components of the metric tensor,  $g = \det(g_{ij})$ , and  $(g^{ij}) = (g_{ij})^{-1}$ . Thus the Laplace operator contains in it **the complete information** about the geometry.

For a graph  $K = (V, E)$  (without loops and double connections) and a real-valued function  $u$  on the set  $V$  of vertices, the combinatorial Laplacian is given by

$$Lu(x) = \sum_{y \sim x} (u(x) - u(y)) = -m(x) \left( \frac{1}{m(x)} \left( \sum_{y \sim x} u(y) \right) - u(x) \right).$$

Note that according to the first expression  $z \sim x$  if and only if  $L\delta_z(x) = -1$ .

## Laplacian in Graph and Riemannian Settings

In Riemannian Geometry the Laplacian on functions is defined as

$$\Delta u = -\frac{1}{\sqrt{g}} \sum \frac{\partial}{\partial x^i} \left( \sqrt{g} g^{ij} \frac{\partial u}{\partial x^j} \right) = -g^{ij} \frac{\partial^2 u}{\partial x^i \partial x^j} + \dots$$

where  $g_{ij}$  are components of the metric tensor,  $g = \det(g_{ij})$ , and  $(g^{ij}) = (g_{ij})^{-1}$ . Thus the Laplace operator contains in it **the complete information** about the geometry.

For a graph  $K = (V, E)$  (without loops and double connections) and a real-valued function  $u$  on the set  $V$  of vertices, the combinatorial Laplacian is given by

$$Lu(x) = \sum_{y \sim x} (u(x) - u(y)) = -m(x) \left( \frac{1}{m(x)} \left( \sum_{y \sim x} u(y) \right) - u(x) \right).$$

Note that according to the first expression  $z \sim x$  if and only if  $L\delta_z(x) = -1$ . Thus the combinatorial Laplacian contains **the full information** about the graph.

## A continuous analog of the second expression for $Lu$ .

We do it in  $\mathbb{R}^2$  to simplify the notation. By Taylor's Theorem

$$u(x, y) = u(x_0, y_0) + (xu_x + yu_y) + (1/2)(x^2u_{xx} + 2xyu_{xy} + y^2u_{yy}) + O(r^3)$$

where the subscripts denote partial derivatives and partials are evaluated at  $(x_0, y_0)$ .

## A continuous analog of the second expression for $Lu$ .

We do it in  $\mathbb{R}^2$  to simplify the notation. By Taylor's Theorem

$$u(x, y) = u(x_0, y_0) + (xu_x + yu_y) + (1/2)(x^2u_{xx} + 2xyu_{xy} + y^2u_{yy}) + O(r^3)$$

where the subscripts denote partial derivatives and partials are evaluated at  $(x_0, y_0)$ . Average over a circle  $C_r$  of small radius  $r > 0$  to yield

$$\frac{1}{2\pi r} \int_{C_r} u \, ds = u(x_0, y_0) - \frac{r^2}{4} \Delta u(x_0, y_0) + O(r^3).$$



## A continuous analog of the second expression for $Lu$ .

We do it in  $\mathbb{R}^2$  to simplify the notation. By Taylor's Theorem

$$u(x, y) = u(x_0, y_0) + (xu_x + yu_y) + (1/2)(x^2u_{xx} + 2xyu_{xy} + y^2u_{yy}) + O(r^3)$$

where the subscripts denote partial derivatives and partials are evaluated at  $(x_0, y_0)$ . Average over a circle  $C_r$  of small radius  $r > 0$  to yield

$$\frac{1}{2\pi r} \int_{C_r} u \, ds = u(x_0, y_0) - \frac{r^2}{4} \Delta u(x_0, y_0) + O(r^3).$$

This translates to

$$\Delta u(x_0, y_0) = - \lim_{r \rightarrow 0} \frac{4}{r^2} \left( \frac{1}{2\pi r} \int_{C_r} u \, ds - u(x_0, y_0) \right).$$

## A continuous analog of the second expression for $Lu$ .

We do it in  $\mathbb{R}^2$  to simplify the notation. By Taylor's Theorem

$$u(x, y) = u(x_0, y_0) + (xu_x + yu_y) + (1/2)(x^2u_{xx} + 2xyu_{xy} + y^2u_{yy}) + O(r^3)$$

where the subscripts denote partial derivatives and partials are evaluated at  $(x_0, y_0)$ . Average over a circle  $C_r$  of small radius  $r > 0$  to yield

$$\frac{1}{2\pi r} \int_{C_r} u \, ds = u(x_0, y_0) - \frac{r^2}{4} \Delta u(x_0, y_0) + O(r^3).$$

This translates to

$$\Delta u(x_0, y_0) = - \lim_{r \rightarrow 0} \frac{4}{r^2} \left( \frac{1}{2\pi r} \int_{C_r} u \, ds - u(x_0, y_0) \right).$$

This is analogous to our second expression for  $Lu$

$$Lu(x) = -m(x) \left( \frac{1}{m(x)} \left( \sum_{y \sim x} u(y) \right) - u(x) \right).$$

# The Maximum Principle

**Proposition.** Suppose  $Lu \geq 0$  and for every  $y \sim x$   $u(y) \geq u(x)$ .  
Then  $u(y) = u(x)$  for every neighbor  $y$  of  $x$ .

# The Maximum Principle

**Proposition.** Suppose  $Lu \geq 0$  and for every  $y \sim x$   $u(y) \geq u(x)$ . Then  $u(y) = u(x)$  for every neighbor  $y$  of  $x$ .

Proof.

$$0 \geq -Lu(x) = \sum_{y \sim x} (u(y) - u(x)) \geq 0$$



# The Maximum Principle

**Proposition.** Suppose  $Lu \geq 0$  and for every  $y \sim x$   $u(y) \geq u(x)$ . Then  $u(y) = u(x)$  for every neighbor  $y$  of  $x$ .

Proof.

$$0 \geq -Lu(x) = \sum_{y \sim x} (u(y) - u(x)) \geq 0$$



The proposition ought to be called "the minimum principle". Applying it to  $-u$  and reversing all inequalities one obtains "the maximum principle." In particular, a harmonic function ( $Lu = 0$ ) cannot attain an "interior" extremum.

## Harnack inequality

**Proposition.** Suppose  $x \sim y$  are two neighboring vertices of  $K$  and  $u \geq 0$  is a function on  $V$  with  $Lu(x) \geq 0$  and  $Lu(y) \geq 0$ . Then

$$\frac{1}{m(y)}u(x) \leq u(y) \leq m(x)u(x).$$

## Harnack inequality

**Proposition.** Suppose  $x \sim y$  are two neighboring vertices of  $K$  and  $u \geq 0$  is a function on  $V$  with  $Lu(x) \geq 0$  and  $Lu(y) \geq 0$ . Then

$$\frac{1}{m(y)}u(x) \leq u(y) \leq m(x)u(x).$$

If  $u(x) > 0$  we get more symmetric inequalities

$$\frac{1}{m(y)} \leq \frac{u(y)}{u(x)} \leq m(x).$$

## Harnack inequality

**Proposition.** Suppose  $x \sim y$  are two neighboring vertices of  $K$  and  $u \geq 0$  is a function on  $V$  with  $Lu(x) \geq 0$  and  $Lu(y) \geq 0$ . Then

$$\frac{1}{m(y)}u(x) \leq u(y) \leq m(x)u(x).$$

If  $u(x) > 0$  we get more symmetric inequalities

$$\frac{1}{m(y)} \leq \frac{u(y)}{u(x)} \leq m(x).$$

Proof.

$$0 \leq Lu(x) = m(x)u(x) - \sum_{x \sim z} u(z) \leq m(x)u(x) - u(y).$$





## Some definitions

$$C^0(K) = \{u : V \longrightarrow \mathbb{R}\}$$

## Some definitions

$$C^0(K) = \{u : V \longrightarrow \mathbb{R}\}$$

$$C_c^0(K) = \{u : V \longrightarrow \mathbb{R} \mid u \text{ has finite support}\}$$

## Some definitions

$$C^0(K) = \{u : V \longrightarrow \mathbb{R}\}$$

$$C_c^0(K) = \{u : V \longrightarrow \mathbb{R} \mid u \text{ has finite support}\}$$

$$C^1(K) = \{\phi : \tilde{E} \longrightarrow \mathbb{R} \mid \phi([x, y]) = -\phi([y, x])\}$$
 where  $\tilde{E}$  is the set of oriented edges of  $K$ .

## Some definitions

$$C^0(K) = \{u : V \longrightarrow \mathbb{R}\}$$

$$C_c^0(K) = \{u : V \longrightarrow \mathbb{R} \mid u \text{ has finite support}\}$$

$C^1(K) = \{\phi : \tilde{E} \longrightarrow \mathbb{R} \mid \phi([x, y]) = -\phi([y, x])\}$  where  $\tilde{E}$  is the set of oriented edges of  $K$ .

$$\ell_{2,0} = \{u : V \longrightarrow \mathbb{R} \mid \sum_{x \in V} u(x)^2 < \infty\}$$

## Some definitions

$$C^0(K) = \{u : V \longrightarrow \mathbb{R}\}$$

$$C_c^0(K) = \{u : V \longrightarrow \mathbb{R} \mid u \text{ has finite support}\}$$

$$C^1(K) = \{\phi : \tilde{E} \longrightarrow \mathbb{R} \mid \phi([x, y]) = -\phi([y, x])\}$$
 where  $\tilde{E}$  is the set of oriented edges of  $K$ .

$$\ell_{2,0} = \{u : V \longrightarrow \mathbb{R} \mid \sum_{x \in V} u(x)^2 < \infty\}$$

$$\ell_{2,1} = \{\phi : \tilde{E} \longrightarrow \mathbb{R} \mid \sum_{[x,y] \in \tilde{E}} \phi([x, y])^2 < \infty\}$$

## Some definitions

$$C^0(K) = \{u : V \longrightarrow \mathbb{R}\}$$

$$C_c^0(K) = \{u : V \longrightarrow \mathbb{R} \mid u \text{ has finite support}\}$$

$$C^1(K) = \{\phi : \tilde{E} \longrightarrow \mathbb{R} \mid \phi([x, y]) = -\phi([y, x])\}$$
 where  $\tilde{E}$  is the set of oriented edges of  $K$ .

$$\ell_{2,0} = \{u : V \longrightarrow \mathbb{R} \mid \sum_{x \in V} u(x)^2 < \infty\}$$

$$\ell_{2,1} = \{\phi : \tilde{E} \longrightarrow \mathbb{R} \mid \sum_{[x,y] \in \tilde{E}} \phi([x, y])^2 < \infty\}$$

The last two spaces become Hilbert spaces if equipped with the natural inner products

$$(u, v) = \sum_{x \in V} u(x)v(x) \quad \text{and} \quad (\phi, \psi) = \frac{1}{2} \sum_{[x,y] \in \tilde{E}} \phi([x, y])\psi([x, y])$$

respectively.

## $L^2$ , self-adjointness, and the spectrum

There are natural maps from functions to cochains and back.

$$du([x, y]) = u(y) - u(x) \quad \text{and} \quad d^* \phi(x) = \sum_{y \sim x} \phi([y, x])$$

which are adjoints with respect to the inner products defined above.  $d$  is the difference analog of the gradient while  $-d^*$  is the analog of the divergence.

## $L^2$ , self-adjointness, and the spectrum

There are natural maps from functions to cochains and back.

$$du([x, y]) = u(y) - u(x) \quad \text{and} \quad d^* \phi(x) = \sum_{y \sim x} \phi([y, x])$$

which are adjoints with respect to the inner products defined above.  $d$  is the difference analog of the gradient while  $-d^*$  is the analog of the divergence. A simple check shows that

$$Lu = d^* d$$

in analogy with

$$\Delta u = -\operatorname{div} \operatorname{grad} u.$$



## $L^2$ , self-adjointness, and the spectrum

There are natural maps from functions to cochains and back.

$$du([x, y]) = u(y) - u(x) \quad \text{and} \quad d^* \phi(x) = \sum_{y \sim x} \phi([y, x])$$

which are adjoints with respect to the inner products defined above.  $d$  is the difference analog of the gradient while  $-d^*$  is the analog of the divergence. A simple check shows that

$$Lu = d^* d$$

in analogy with

$$\Delta u = -\operatorname{div} \operatorname{grad} u.$$

Clearly

$$(Lu, v) = (d^* du, v) = (du, dv)$$

if at least one of  $u, v$  has finite support.

## $L^2$ , self-adjointness, and the spectrum - continued

Our graphs will be always connected and for the most part infinite. If the valence function  $m(x)$  is bounded, the Laplacian is a bounded operator on  $\ell_2(K)$ . It is also symmetric and hence self-adjoint.

## $L^2$ , self-adjointness, and the spectrum - continued

Our graphs will be always connected and for the most part infinite. If the valence function  $m(x)$  is bounded, the Laplacian is a bounded operator on  $\ell_2(K)$ . It is also symmetric and hence self-adjoint. In general, when the valence is not bounded we have

**Theorem.**  $L$  with the domain  $C_c^0(K)$  is a symmetric, positive, essentially self-adjoint operator on  $\ell_2(K)$ .

## $L^2$ , self-adjointness, and the spectrum - continued

Our graphs will be always connected and for the most part infinite. If the valence function  $m(x)$  is bounded, the Laplacian is a bounded operator on  $\ell_2(K)$ . It is also symmetric and hence self-adjoint. In general, when the valence is not bounded we have

**Theorem.**  $L$  with the domain  $C_c^0(K)$  is a symmetric, positive, essentially self-adjoint operator on  $\ell_2(K)$ .

This is analogous to the fact that the Laplacian  $\Delta$  on a complete Riemannian manifold  $M$  with the domain  $C_0^\infty(M)$  is essentially self-adjoint.

## $L^2$ , self-adjointness, and the spectrum - continued

Our graphs will be always connected and for the most part infinite. If the valence function  $m(x)$  is bounded, the Laplacian is a bounded operator on  $\ell_2(K)$ . It is also symmetric and hence self-adjoint. In general, when the valence is not bounded we have

**Theorem.**  $L$  with the domain  $C_c^0(K)$  is a symmetric, positive, essentially self-adjoint operator on  $\ell_2(K)$ .

This is analogous to the fact that the Laplacian  $\Delta$  on a complete Riemannian manifold  $M$  with the domain  $C_0^\infty(M)$  is essentially self-adjoint.

In view of the theorem we can talk unambiguously about the spectrum of  $L$  and derive invariants of the graph from it.

## $L^2$ , self-adjointness, and the spectrum - continued

Our graphs will be always connected and for the most part infinite. If the valence function  $m(x)$  is bounded, the Laplacian is a bounded operator on  $\ell_2(K)$ . It is also symmetric and hence self-adjoint. In general, when the valence is not bounded we have

**Theorem.**  $L$  with the domain  $C_c^0(K)$  is a symmetric, positive, essentially self-adjoint operator on  $\ell_2(K)$ .

This is analogous to the fact that the Laplacian  $\Delta$  on a complete Riemannian manifold  $M$  with the domain  $C_0^\infty(M)$  is essentially self-adjoint.

In view of the theorem we can talk unambiguously about the spectrum of  $L$  and derive invariants of the graph from it. In particular,

$$\lambda_0(K) = \inf\{\lambda \in \text{Spec}(L)\} = \inf\left\{\frac{(du, du)}{(u, u)} \mid u \in C_c^0(K) \setminus \{0\}\right\}$$

is a very important one.

# Cheeger's constant and bounds on $\lambda_0(K)$

Define, for a finite subgraph  $N$  of  $K$ ,

$$h(N) = \frac{\#\{x \in V \mid x \in N, \exists y \in V, y \notin N, y \sim x\}}{\#\{y \in V \mid y \in N\}} = \frac{L(\partial N)}{A(N)}$$

# Cheeger's constant and bounds on $\lambda_0(K)$

Define, for a finite subgraph  $N$  of  $K$ ,

$$h(N) = \frac{\#\{x \in V \mid x \in N, \exists y \in V, y \notin N, y \sim x\}}{\#\{y \in V \mid y \in N\}} = \frac{L(\partial N)}{A(N)}$$

and

$$h = h(K) = \inf_N h(N).$$



# Cheeger's constant and bounds on $\lambda_0(K)$

Define, for a finite subgraph  $N$  of  $K$ ,

$$h(N) = \frac{\#\{x \in V \mid x \in N, \exists y \in V, y \notin N, y \sim x\}}{\#\{y \in V \mid y \in N\}} = \frac{L(\partial N)}{A(N)}$$

and

$$h = h(K) = \inf_N h(N).$$

**Theorem.** Suppose  $K$  satisfies  $m(x) \leq m$  for all  $x \in V$ . Then

$$\frac{h^2}{2m} \leq \lambda_0(K) \leq h.$$

## Comments on Cheeger Inequality

- ▶ The proof of the lower bound was motivated by and followed the same pattern as the proof of corresponding result in Riemannian Geometry.

## Comments on Cheeger Inequality

- ▶ The proof of the lower bound was motivated by and followed the same pattern as the proof of corresponding result in Riemannian Geometry.
- ▶ An analog for finite graphs is more important and gave rise to an explosion of research on expanding graphs.

# Comments on Cheeger Inequality

- ▶ The proof of the lower bound was motivated by and followed the same pattern as the proof of corresponding result in Riemannian Geometry.
- ▶ An analog for finite graphs is more important and gave rise to an explosion of research on expanding graphs.
- ▶ The appearance of  $m$  in the denominator of the lower bound is counterintuitive. Understanding the formulation that would not have this defect came in a recent work of Bauer, Keller and Wojciechowski using the new notion of intrinsic metric on a graph to modify the way that the size of the boundary is measured.

# Cheeger constant and smallest positive eigenvalue for finite graphs

For finite graphs  $\lambda_0 = 0$  (constant eigenfunction).

# Cheeger constant and smallest positive eigenvalue for finite graphs

For finite graphs  $\lambda_0 = 0$  (constant eigenfunction). One looks instead at

$$\lambda_1 = \inf_{u \neq 0, \sum_{x \in V} u(x) = 0} \left\{ \frac{(du, du)}{(u, u)} \right\}.$$

## Cheeger constant and smallest positive eigenvalue for finite graphs

For finite graphs  $\lambda_0 = 0$  (constant eigenfunction). One looks instead at

$$\lambda_1 = \inf_{u \neq 0, \sum_{x \in V} u(x) = 0} \left\{ \frac{(du, du)}{(u, u)} \right\}.$$

The appropriate isoperimetric (Cheeger) constant is

$$h = h(K) = \inf_{N \subset V, |N| \leq (1/2)|V|} \frac{L(\partial N)}{A(N)}$$

and the estimates above hold for  $\lambda_1$  and  $h$  i.e.

$$\frac{h^2}{2m} \leq \lambda_1(K) \leq h.$$

It is worth pointing out that the two results (about  $\lambda_0$  for infinite graphs and  $\lambda_1$  for finite ones, at least the lower bounds, are proved in practically the same way.

To see the connection note that the first eigenfunction  $\phi_1$  of  $L$  is perpendicular to constants, i.e.  $\sum_{x \in V} \phi(x) = 0$ . Replacing  $\phi$  by its negative if necessary, we can assume that  $\#\{x \in V \mid \phi(x) > 0\} \leq (1/2)\#V$ .



To see the connection note that the first eigenfunction  $\phi_1$  of  $L$  is perpendicular to constants, i.e.  $\sum_{x \in V} \phi(x) = 0$ . Replacing  $\phi$  by its negative if necessary, we can assume that  $\#\{x \in V \mid \phi(x) > 0\} \leq (1/2)\#V$ . Define  $\phi_+ = \max(\phi, 0)$ . We then have

$$\lambda_1 = \frac{(L\phi, \phi_+)}{(\phi_+, \phi_+)} \geq \frac{(L\phi_+, \phi_+)}{(\phi_+, \phi_+)} = \frac{(d\phi_+, d\phi_+)}{(\phi_+, \phi_+)}$$

since for points  $x$  where  $\phi(x) > 0$   $L\phi(x) \geq L\phi_+(x)$ .

To see the connection note that the first eigenfunction  $\phi_1$  of  $L$  is perpendicular to constants, i.e.  $\sum_{x \in V} \phi(x) = 0$ . Replacing  $\phi$  by its negative if necessary, we can assume that  $\#\{x \in V \mid \phi(x) > 0\} \leq (1/2)\#V$ . Define  $\phi_+ = \max(\phi, 0)$ . We then have

$$\lambda_1 = \frac{(L\phi, \phi_+)}{(\phi_+, \phi_+)} \geq \frac{(L\phi_+, \phi_+)}{(\phi_+, \phi_+)} = \frac{(d\phi_+, d\phi_+)}{(\phi_+, \phi_+)}$$

since for points  $x$  where  $\phi(x) > 0$   $L\phi(x) \geq L\phi_+(x)$ . Thus to give a lower bound for  $\lambda_1$  we estimate the Rayleigh-Ritz quotient of a function with finite support which is precisely what we need to do to estimate  $\lambda_0$  in the case of an infinite graph.

# Surjectivity of the Laplacian

T. Ceccherini-Silberstein, M. Coornaert, JD

**Theorem.** Suppose  $K$  is an infinite connected graph. Then  $L : C^0(K) \rightarrow C^0(K)$  is surjective.

## Remarks.

- ▶ For finite graphs, the image of  $L$  is perpendicular to constants.
- ▶ The proof uses only the maximum principle. Therefore the theorem holds for a large class of operators.

**Outline of proof.** Consider the equation  $Lu = f$  for a fixed, arbitrary  $f$ .

**Step 1.** Take an exhaustion of the graph by finite subgraphs and solve the difference equation on each subgraph.

**Step 2.** Pass to the limit to get the solution on the whole graph.

## Step 1

Fix  $x_0 \in V$  and consider  $B_n = \{x \in V \mid d(x, x_0) \leq n\}$ . Let  $K_n$  be the full subgraph with  $B_n$  as the set of vertices. Let  $F_n$  be the set of all real-valued functions on  $B_n$ . Define  $L_n : F_n \rightarrow F_n$  as follows.

$$L_n u = (L\tilde{u})|_{B_n}$$

where  $\tilde{u}$  denotes the extension by zero of  $u$  to  $V$ .

## Step 1

Fix  $x_0 \in V$  and consider  $B_n = \{x \in V \mid d(x, x_0) \leq n\}$ . Let  $K_n$  be the full subgraph with  $B_n$  as the set of vertices. Let  $F_n$  be the set of all real-valued functions on  $B_n$ . Define  $L_n : F_n \rightarrow F_n$  as follows.

$$L_n u = (L\tilde{u})|_{B_n}$$

where  $\tilde{u}$  denotes the extension by zero of  $u$  to  $V$ .

**Lemma.**  $L_n$  is surjective.

**Proof.**

We show that  $L_n$  is injective. Suppose  $u \in F_n$  is in the kernel of  $L_n$ . Then  $\tilde{u}$  is harmonic on  $B_n$  and vanishes on its boundary. By the maximum principle  $\tilde{u}$  and hence  $u$  are identically zero.  $\square$

Fix  $f \in C^0(K)$ . The lemma implies that the set  $S_n = \{u \in F_n \mid L_n u = f|_{B_n}\}$  is nonempty for every  $n$ .

## Step 2

For  $m \geq n$ , let  $r_{m,n} : F_m \rightarrow F_n$  be the restriction  $r_{m,n}u = u|_{B_n}$ .  
Consider the sets

$$X_{m,n} = r_{m,n}(S_m) \subset F_n.$$

## Step 2

For  $m \geq n$ , let  $r_{m,n} : F_m \rightarrow F_n$  be the restriction  $r_{m,n}u = u|_{B_n}$ . Consider the sets

$$X_{m,n} = r_{m,n}(S_m) \subset F_n.$$

These sets are affine subspaces of  $F_n$ , are nonempty by the Lemma, and form a decreasing sequence, i.e.  $X_{m+1,n} \subset X_{m,n}$ . It follows that they stabilize in the sense that there exists  $m_0(n)$  such that  $X_{m_0(n),n} = \bigcap_{m \geq n} X_{m,n} =: U_n$ .

## Step 2

For  $m \geq n$ , let  $r_{m,n} : F_m \rightarrow F_n$  be the restriction  $r_{m,n}u = u|_{B_n}$ . Consider the sets

$$X_{m,n} = r_{m,n}(S_m) \subset F_n.$$

These sets are affine subspaces of  $F_n$ , are nonempty by the Lemma, and form a decreasing sequence, i.e.  $X_{m+1,n} \subset X_{m,n}$ . It follows that they stabilize in the sense that there exists  $m_0(n)$  such that  $X_{m_0(n),n} = \bigcap_{m \geq n} X_{m,n} =: U_n$ .

**Lemma.** For every  $n \geq 1$ ,  $r_{n+1,n} : U_{n+1} \rightarrow U_n$  is surjective.



## Step 2

For  $m \geq n$ , let  $r_{m,n} : F_m \rightarrow F_n$  be the restriction  $r_{m,n}u = u|_{B_n}$ . Consider the sets

$$X_{m,n} = r_{m,n}(S_m) \subset F_n.$$

These sets are affine subspaces of  $F_n$ , are nonempty by the Lemma, and form a decreasing sequence, i.e.  $X_{m+1,n} \subset X_{m,n}$ . It follows that they stabilize in the sense that there exists  $m_0(n)$  such that  $X_{m_0(n),n} = \bigcap_{m \geq n} X_{m,n} =: U_n$ .

**Lemma.** For every  $n \geq 1$ ,  $r_{n+1,n} : U_{n+1} \rightarrow U_n$  is surjective.

**Proof.**

Take  $u \in U_n$  and choose  $m \geq \max\{m_0(n), m_0(n+1)\}$ . There exists  $v \in S_m$  such that  $r_{m,n}v = u$ . Now  $u' = r_{m,n+1}v \in U_{n+1}$  and  $r_{n+1,n}u' = u$ . □

Now take  $u_1 \in U_1$  and choose inductively  $u_{n+1} \in U_{n+1}$  so that  $u_{n+1}|_{B_n} = u_n$ . Then define  $u$  on  $V$  by  $u(x) = u_n(x)$  if  $x \in B_n$ . Clearly,  $u$  is well defined and satisfies  $Lu = f$ .